Active Learning of Points-To Specifications

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```
int main(int argc, char **argv) {
  char *keys;
  size_t keycc, oldcc, keyalloc;
  bool with_filenames;
  size_t cc;
  int opt, prepended;
  int prev_optind, last_recursive;
  int fread_errno;
  intmax_t default_context;
  FILE *fp;
  exit_failure = EXIT_TROUBLE;
  initialize_main (&argc, &argv);
  set_program_name (argv[0]);
  program_name = argv[0];
  // ...
}
```

Android app

security analyst

malware?

Find **malicious behaviors** using source to sink **taint flows**

Information leak:	location	flows to	Internet
SMS Fraud:	phone #	used in	SMS send
Ransomware:	network packets	encrypt	files

```
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  char *keys;
  size_t keycc, oldcc, keyalloc;
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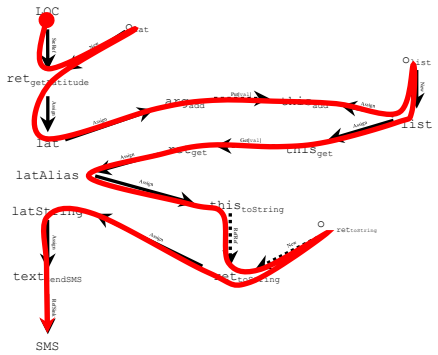
  initialize_main (&argc, &argv);
  set_program_name (argv[0]);
  program_name = argv[0];
  // ...
}
```



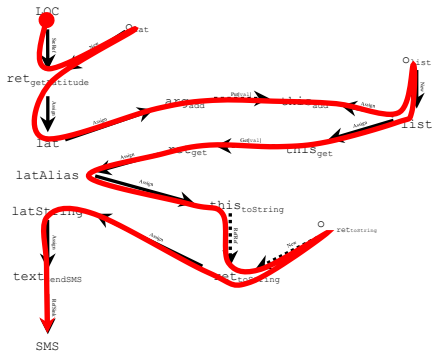
location → Internet
SMS → Internet

Android app

taint analysis

malicious behaviors

```
int main(int argc, char **argv) {
  char *keys;
  size_t keycc, oldcc, keyalloc;
  bool with_filenames;
  framework
  int prev_optind, last_recursive;
  int fread_errno;
  intmax_t default_context;
  FILE *fp;
  exit_failure = EXIT_TROUBLE;
  initialize_main (&argc, &argv);
  framework
  // ...
}
```



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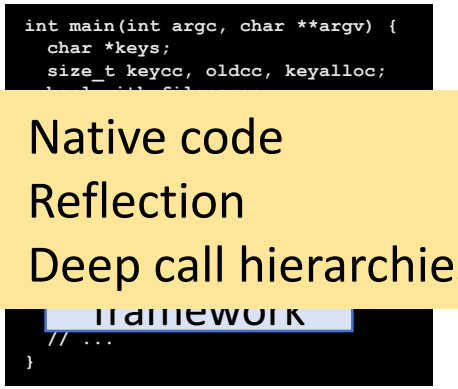
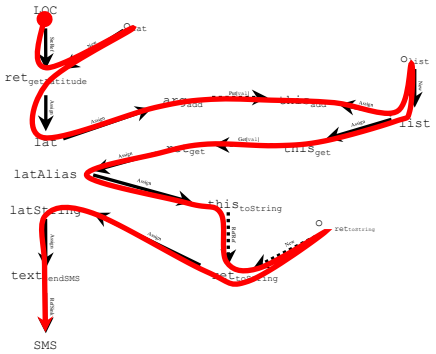


- Native code
- Reflection
- Deep call hierarchies

Android app



taint analysis

location → Internet
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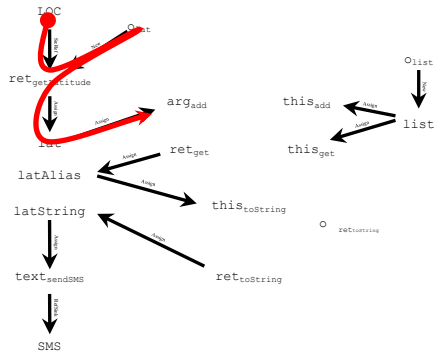
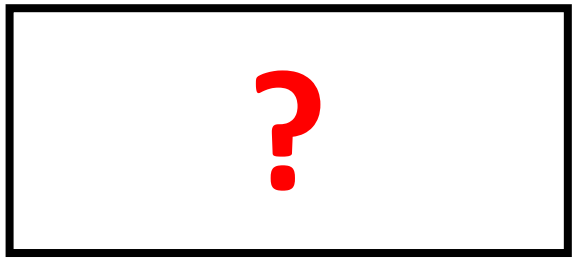
malicious behaviors

```
int main(int argc, char **argv) {
  char *keys;
  size_t keycc, oldcc, keyalloc;
  bool with_filenames;
  [redacted]
  int prev_optind, last_recursive;
  int fread_errno;
  intmax_t default_context;
  FILE *fp;
  exit_failure = EXIT_TROUBLE;
  initialize_main (&argc, &argv);
  [redacted]
  // ...
}
```



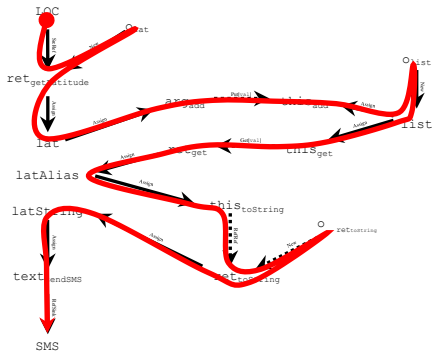


Android app

taint analysis

malicious behaviors

```
int main(int argc, char **argv) {
  char *keys;
  size_t keycc, oldcc, keyalloc;
  bool with_filenames;
  specifications
  int fread_errno;
  intmax_t default_context;
  FILE *fp;
  exit_failure = EXIT_TROUBLE;
  initialize_main (&argc, &argv);
  specifications
}
```



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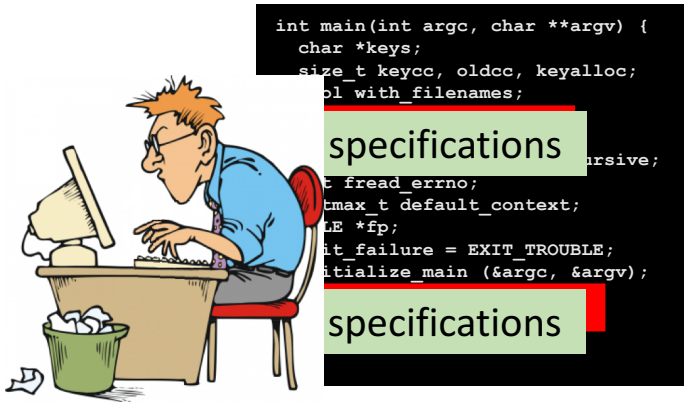
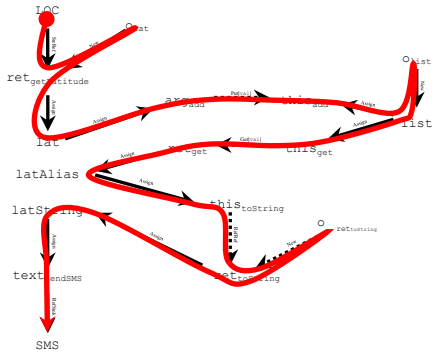


Android app



taint analysis

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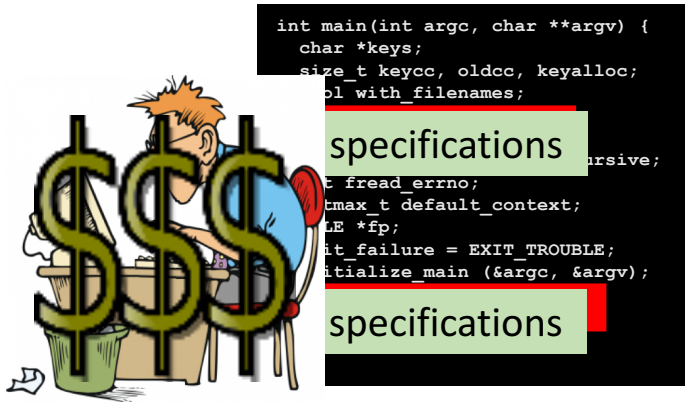
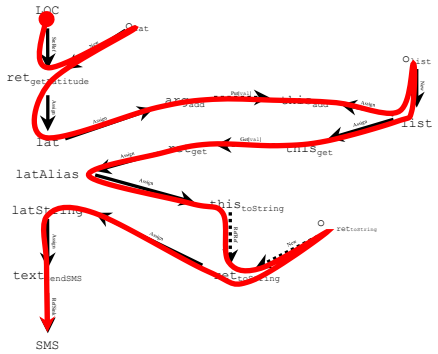


Android app



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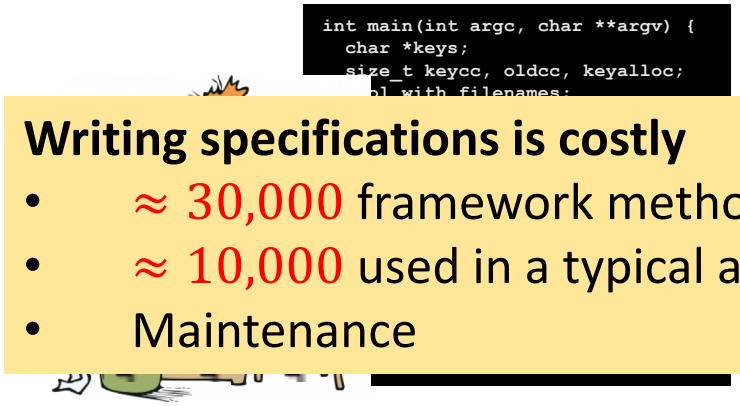
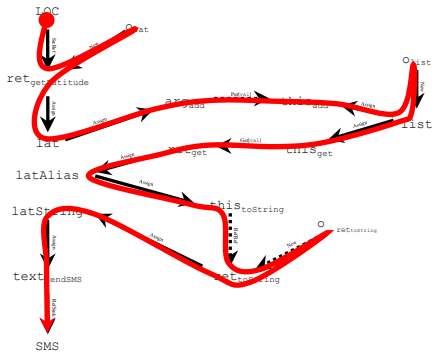


Writing specifications is costly

- ≈ 30,000 framework methods
- ≈ 10,000 used in a typical app
- Maintenance



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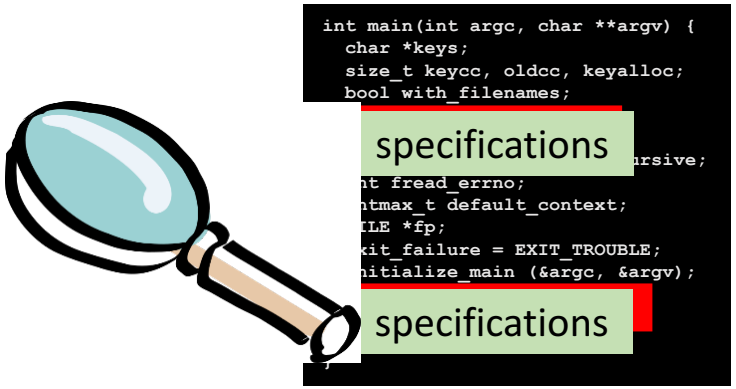
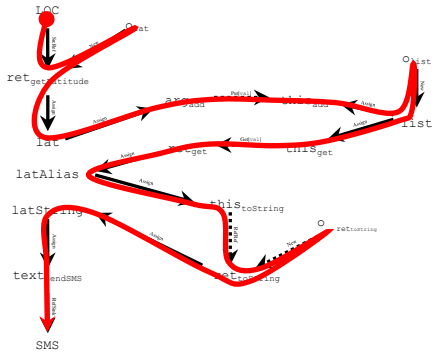


Android app



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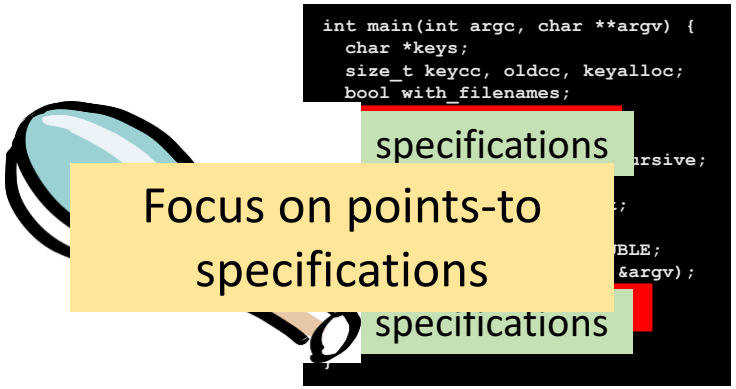

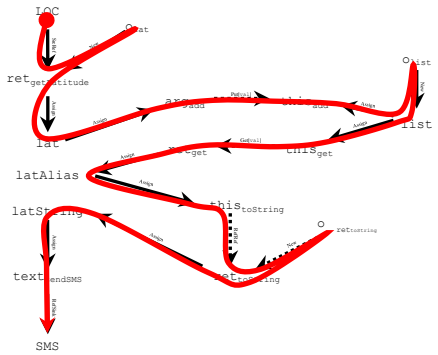

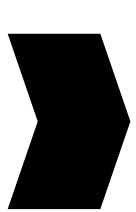

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Android app

taint analysis

malicious behaviors

Roadmap

- Points-to analysis
- Path specifications
- Inference algorithm
- Evaluation

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- **Points-to analysis**
- Path specifications
- Inference algorithm
- Evaluation

Points-To Analysis

```
1 .  Double val = new Double(0.0);
2 .  Box box = new Box();
3 .  box.set(val);
4 .  Box boxAlias = box;
5 .  Double valAlias = boxAlias.get();
```

```
6 .  class Box:  // library
7 .      Object f;
8 .      void set(Object ob): f = ob;
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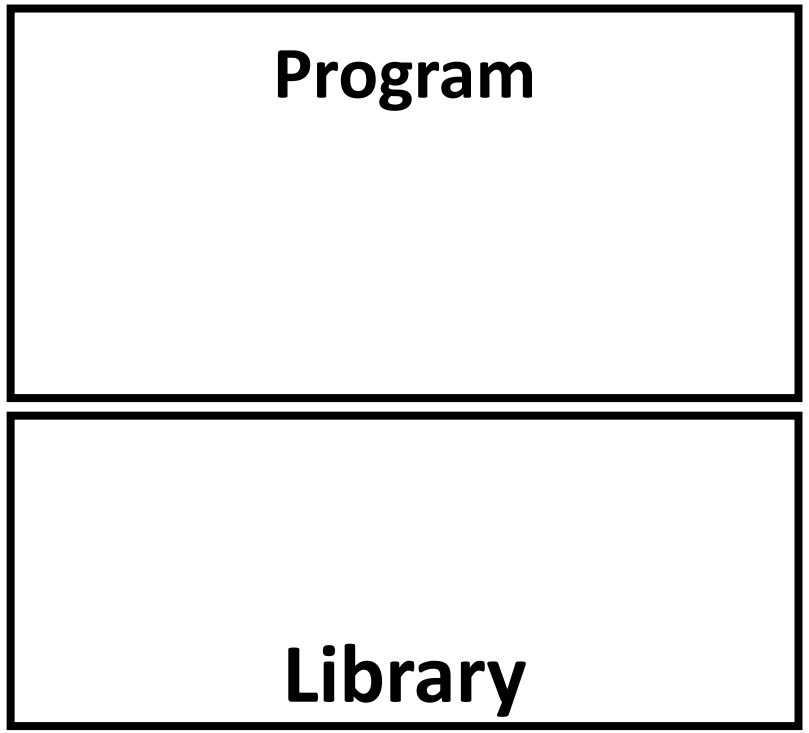
```



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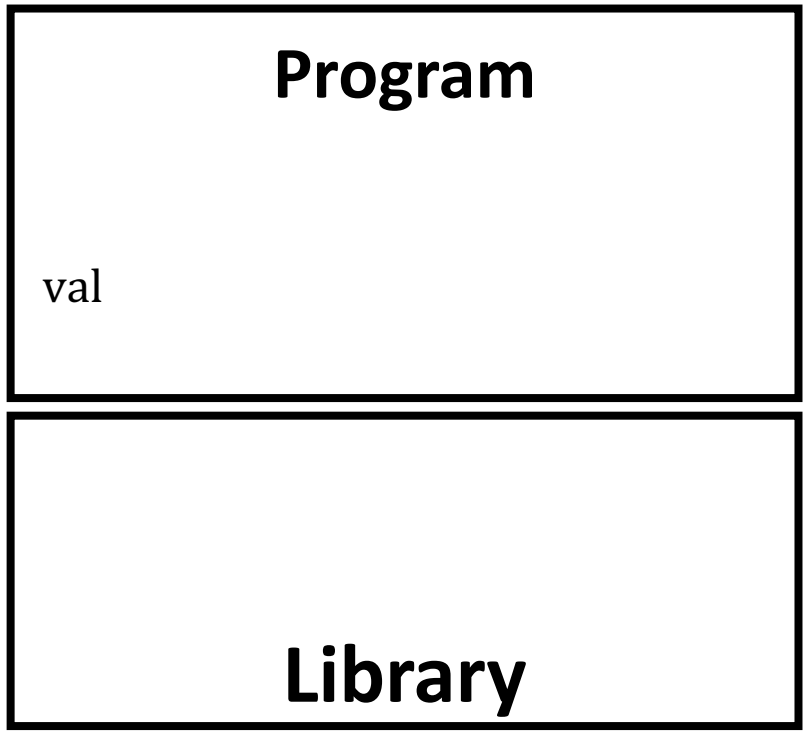

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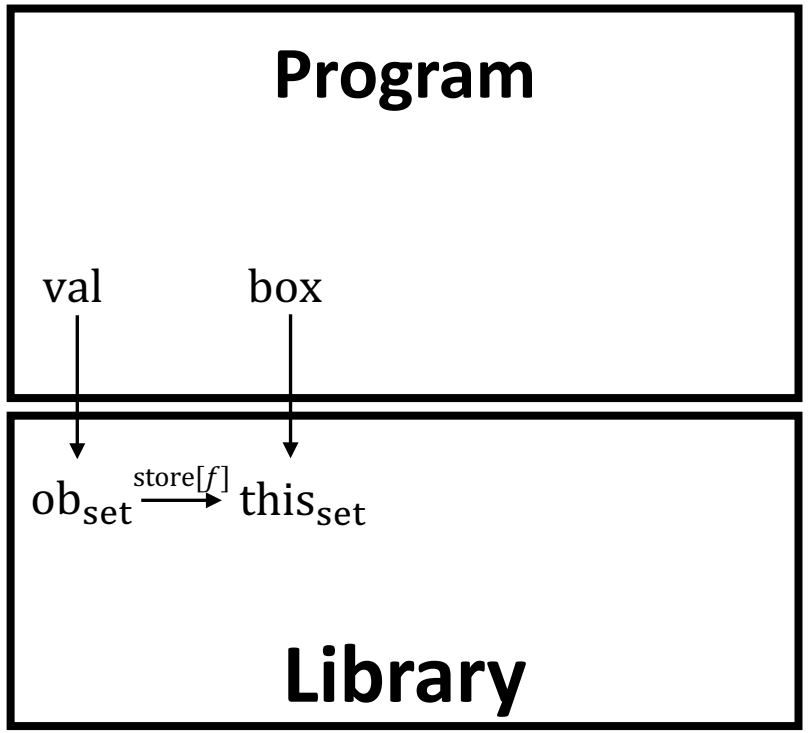

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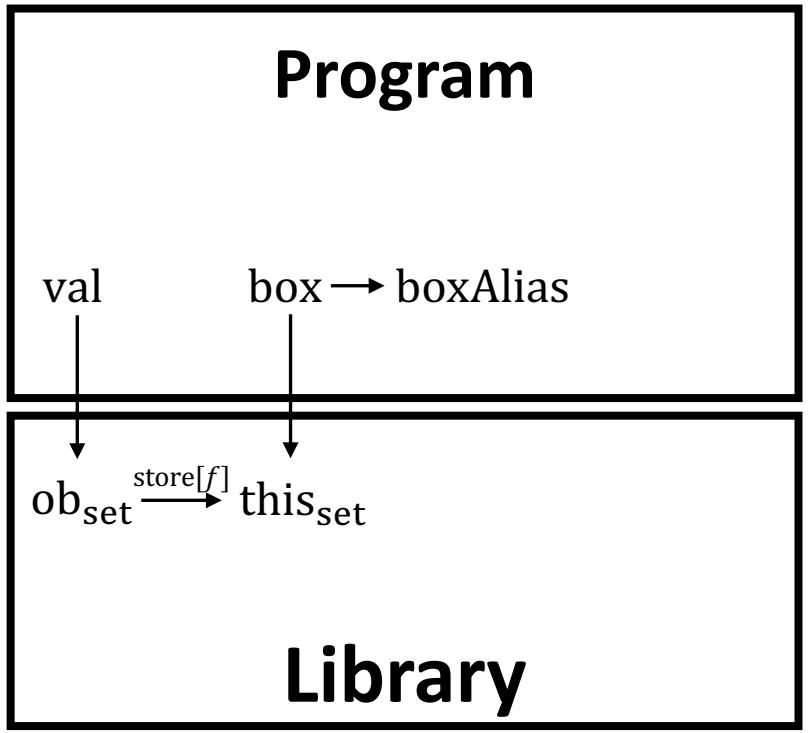

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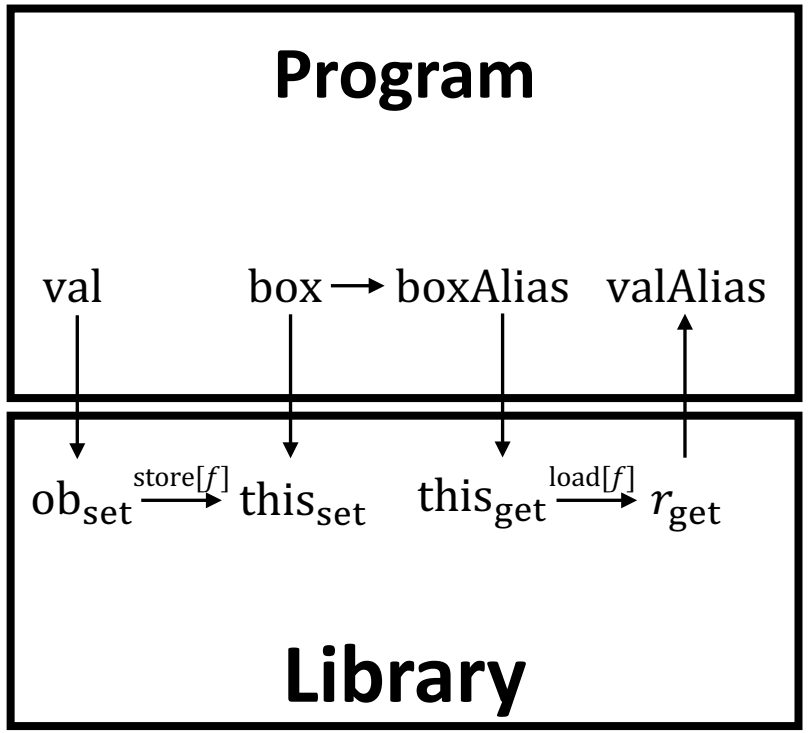

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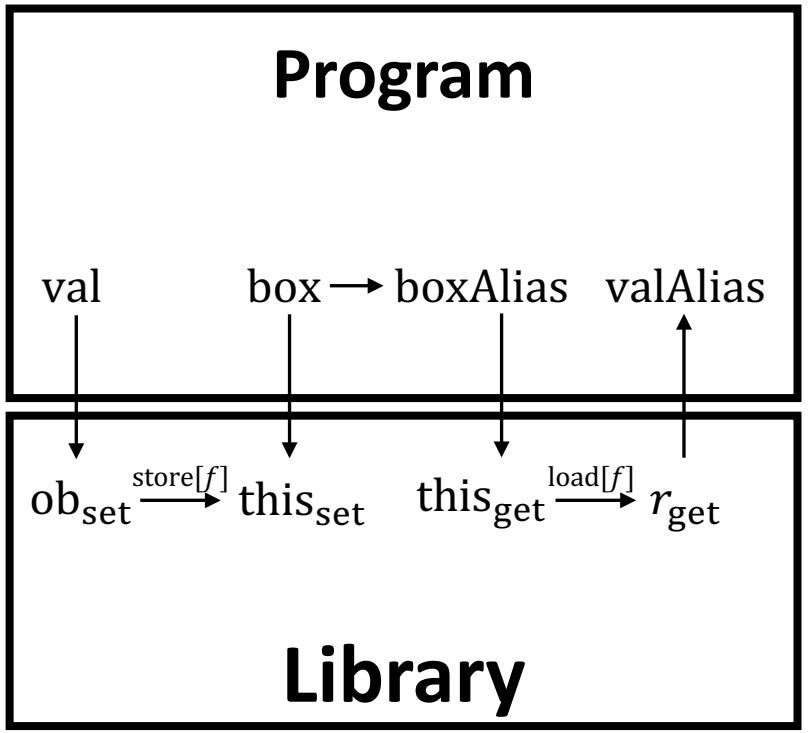
$$\Rightarrow \quad v \xrightarrow{\text{alias}} v$$



Points-To Analysis

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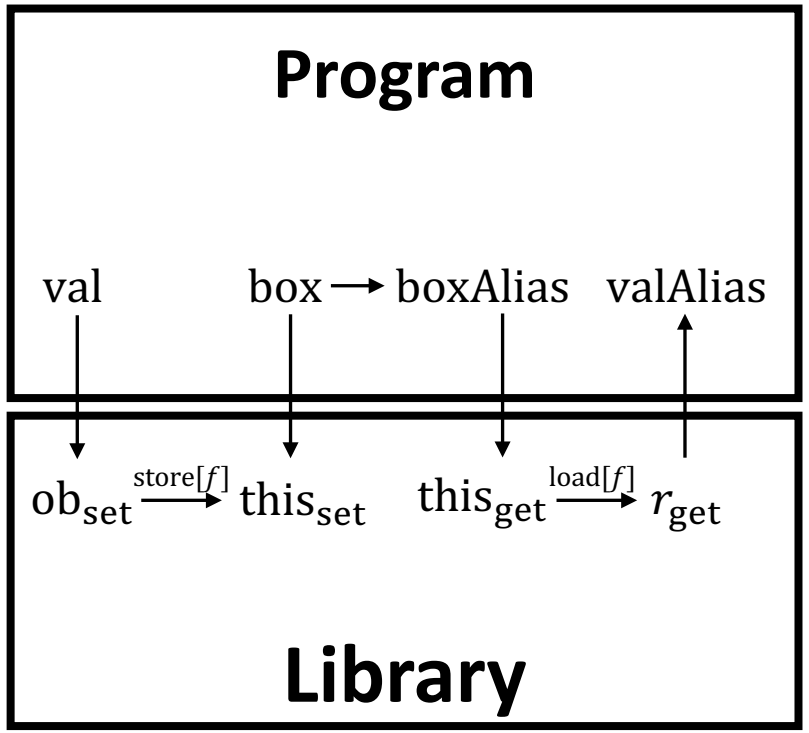
$$\Rightarrow \quad v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$



Points-To Analysis

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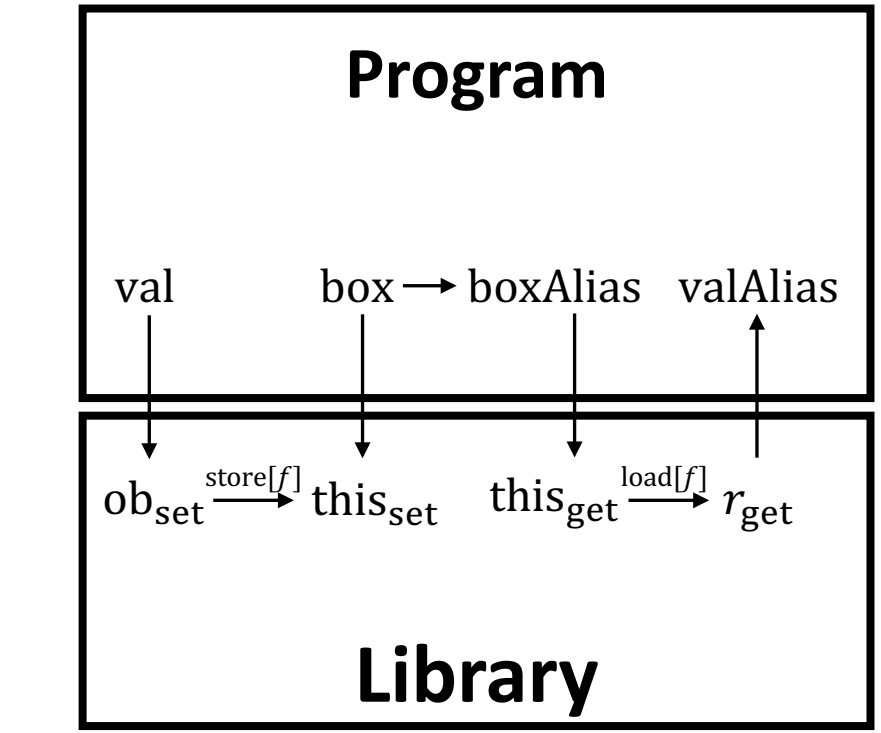

$$\Rightarrow \quad v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

$$u \xrightarrow{\text{alias}} v \to w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

Points-To Analysis

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1 .  Double val = new Double(0.0);
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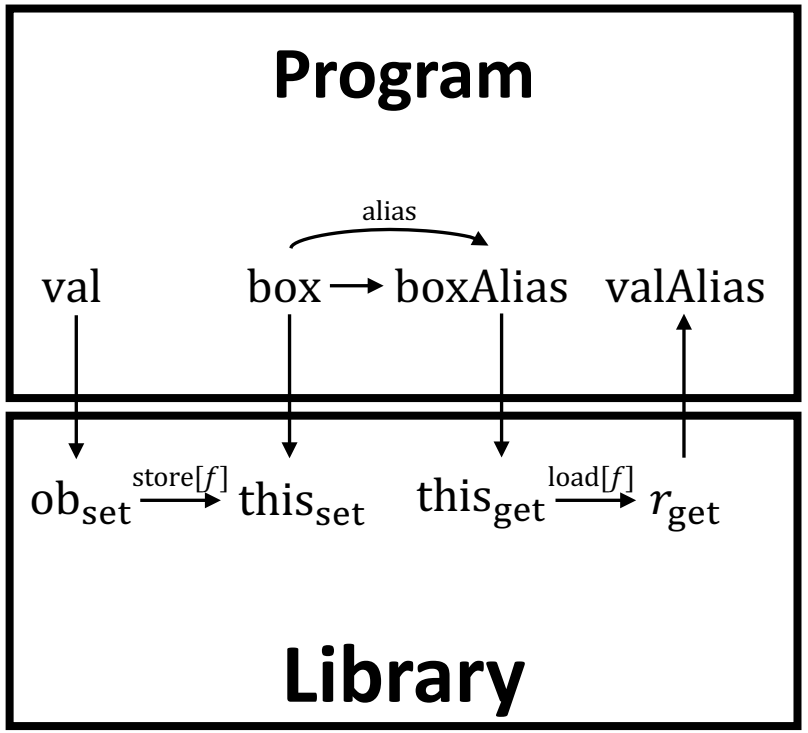

$$u \xrightarrow{\text{alias}} v \Rightarrow v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \Rightarrow u \xrightarrow{\text{alias}} w$$

$$u \xrightarrow{\text{alias}} v \rightarrow w \Rightarrow u \xrightarrow{\text{alias}} w$$

Points-To Analysis

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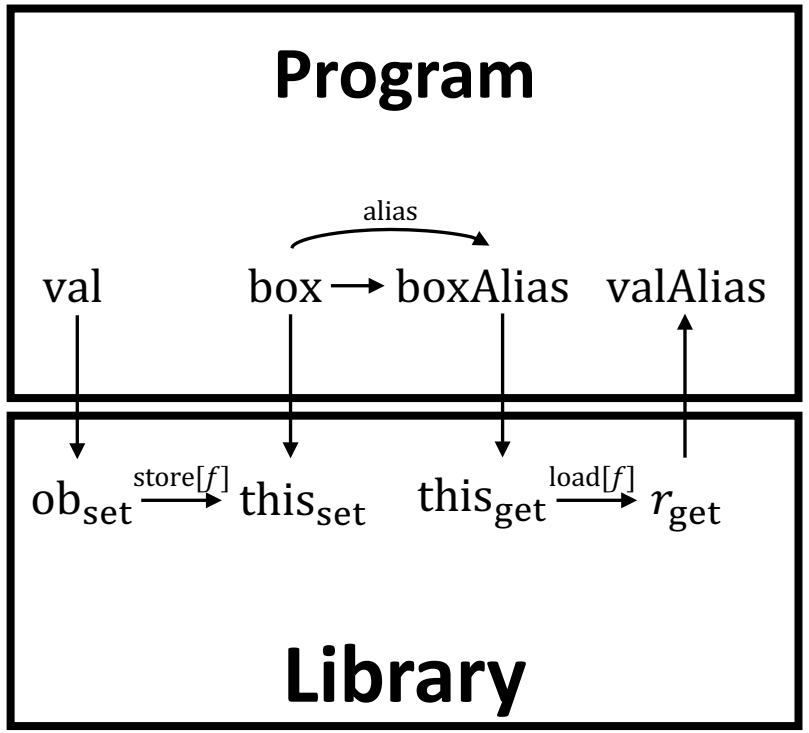

$$\Rightarrow \quad v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

$$u \xrightarrow{\text{alias}} v \rightarrow w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

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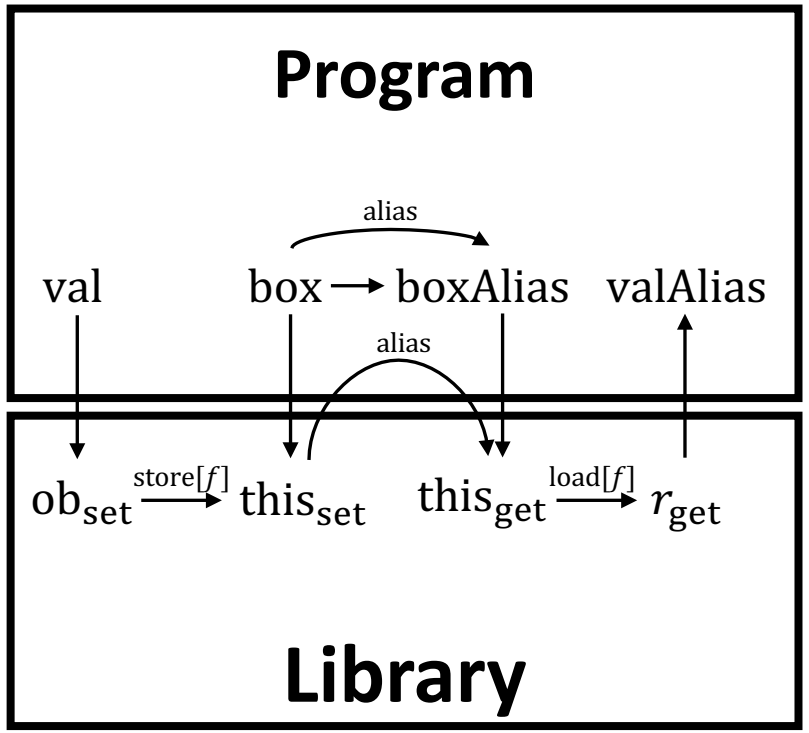

$$\Rightarrow \quad v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

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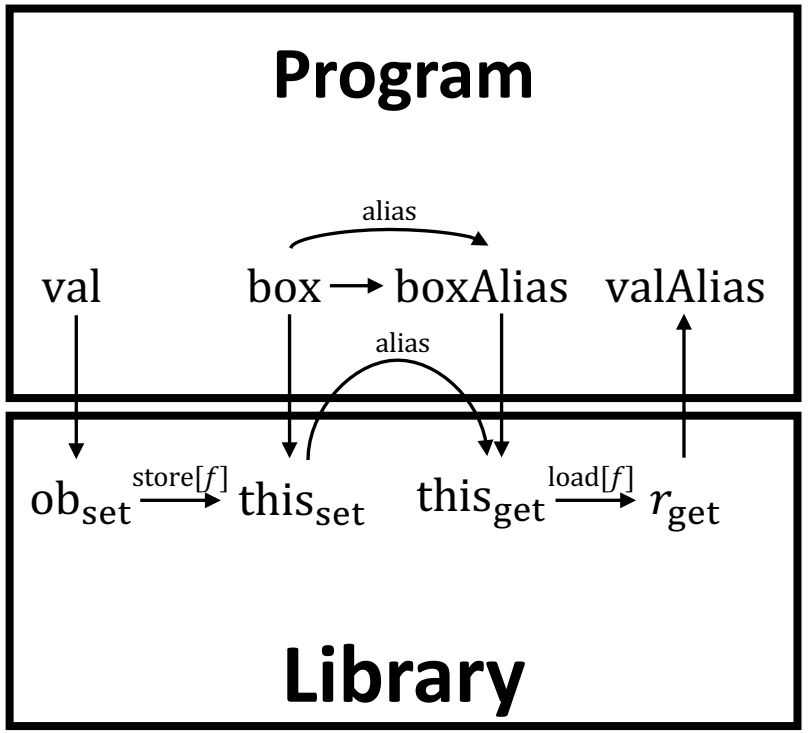

$$v \xrightarrow{\text{alias}} v \quad \Rightarrow \quad v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

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$$u \xrightarrow{\text{alias}} v \leftarrow w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

$$u \xrightarrow{\text{store[f]}} v \xrightarrow{\text{alias}} w \xrightarrow{\text{load[f]}} x \quad \Rightarrow \quad u \xrightarrow{\text{alias}} x$$

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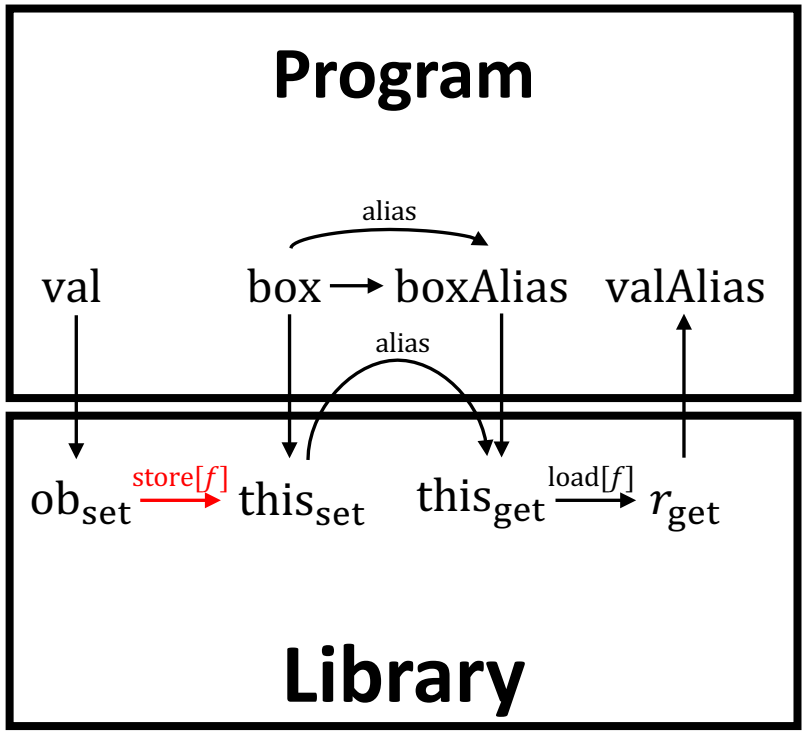

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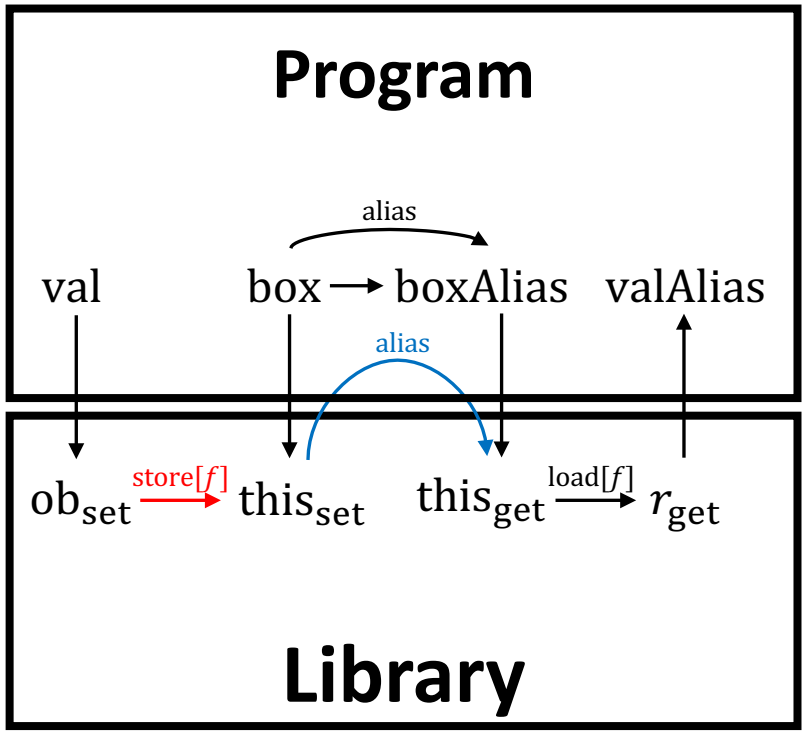

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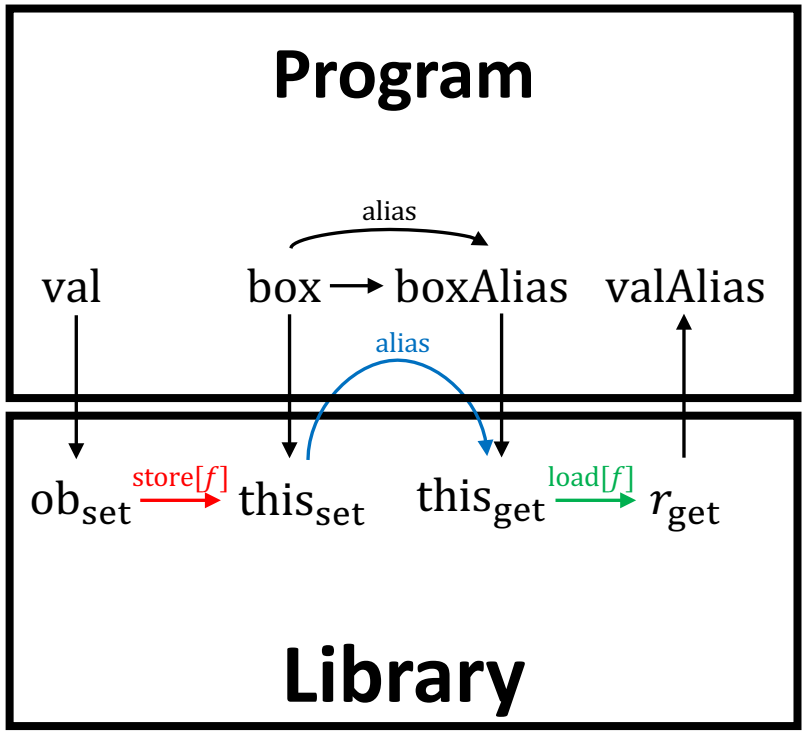

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \Rightarrow u \xrightarrow{\text{alias}} w$$

$$v \xrightarrow{\text{alias}} v \Rightarrow u \xrightarrow{\text{alias}} w$$

$$u \xrightarrow{\text{alias}} v \rightarrow w \Rightarrow u \xrightarrow{\text{alias}} w$$

$$u \xrightarrow{\text{alias}} v \leftarrow w \Rightarrow u \xrightarrow{\text{alias}} w$$

$$u \xrightarrow{\text{store[f]}} v \xrightarrow{\text{alias}} w \xrightarrow{\text{load[f]}} x \Rightarrow u \xrightarrow{\text{alias}} x$$

Points-To Analysis

1. **Double** val = **new Double**(0.0);
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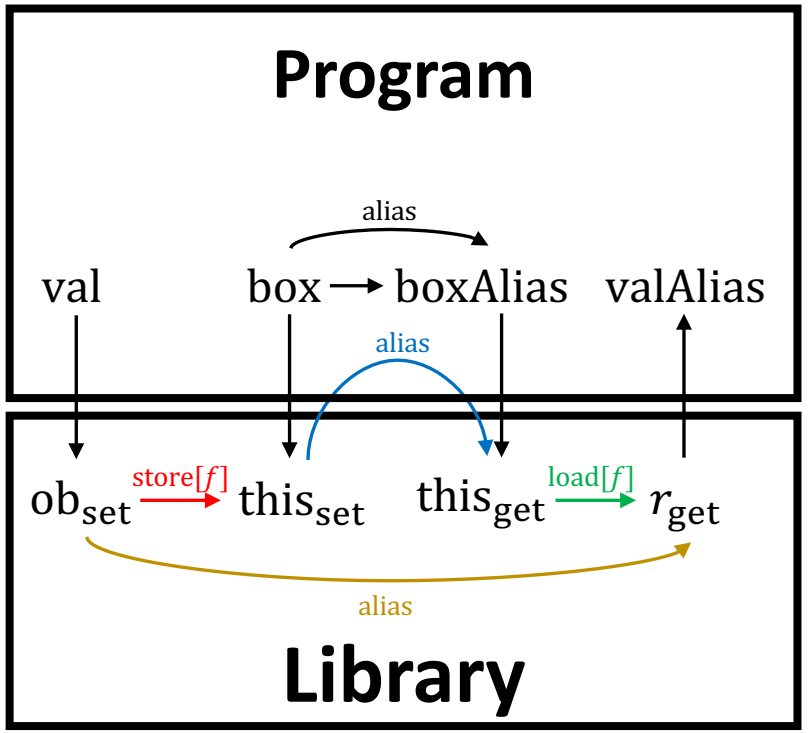

$$\Rightarrow \quad v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

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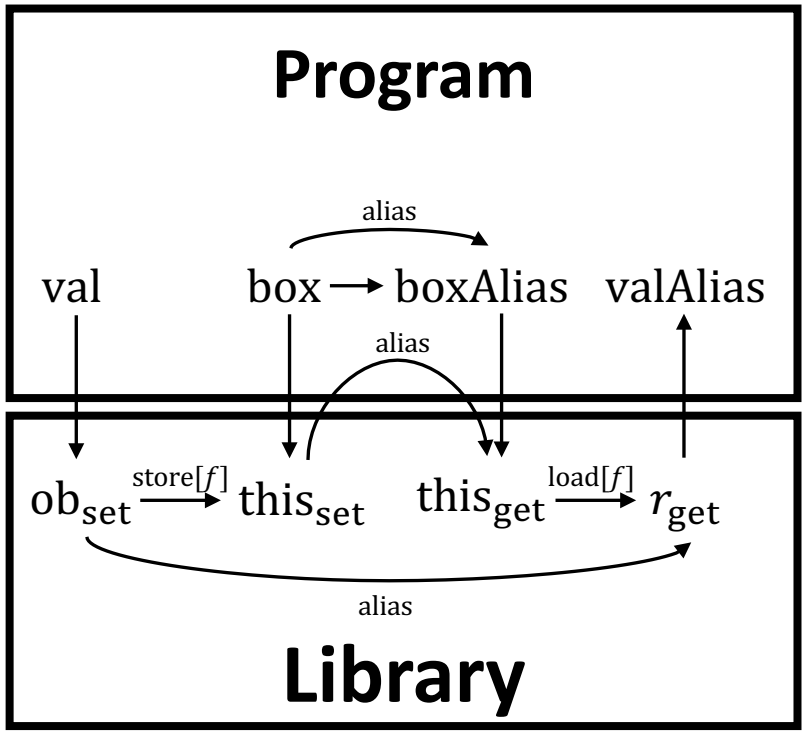

$$v \xrightarrow{\text{alias}} v \quad \Rightarrow \quad v \xrightarrow{\text{alias}} v$$

$$u \xrightarrow{\text{alias}} v \xrightarrow{\text{alias}} w \quad \Rightarrow \quad u \xrightarrow{\text{alias}} w$$

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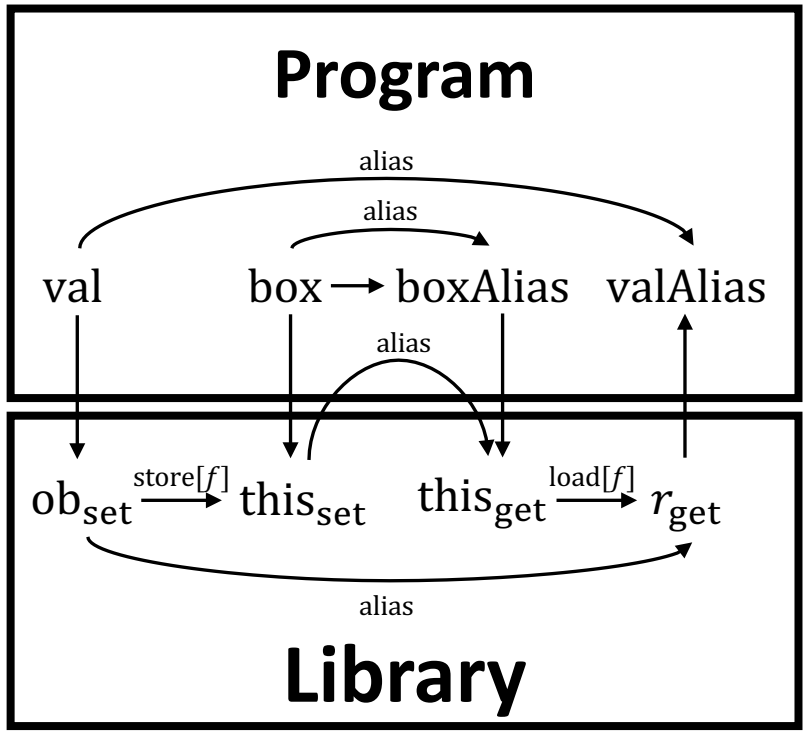

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Points-To Analysis

```
1. Double val = new Double(0.0);
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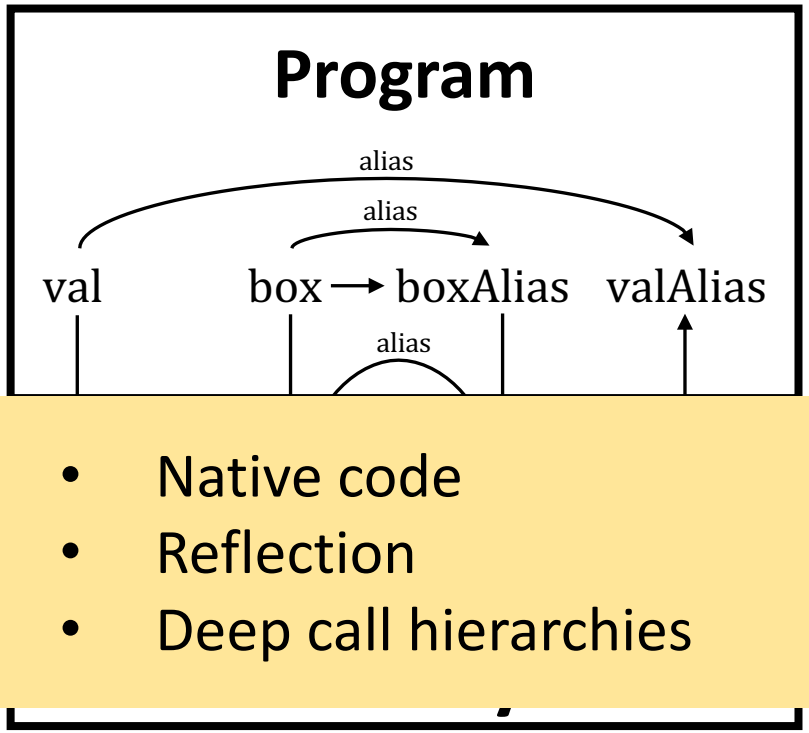

- Native code
- Reflection
- Deep call hierarchies

$$\Rightarrow \quad v \xrightarrow{\text{alias}} v$$

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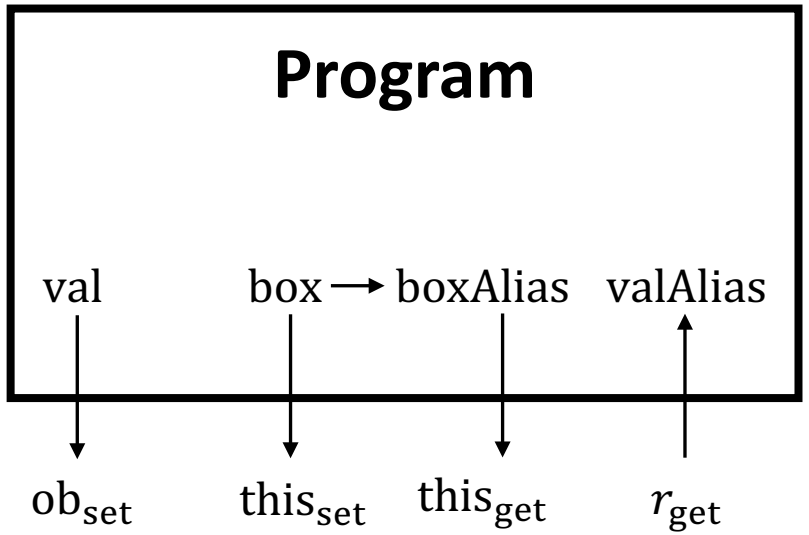

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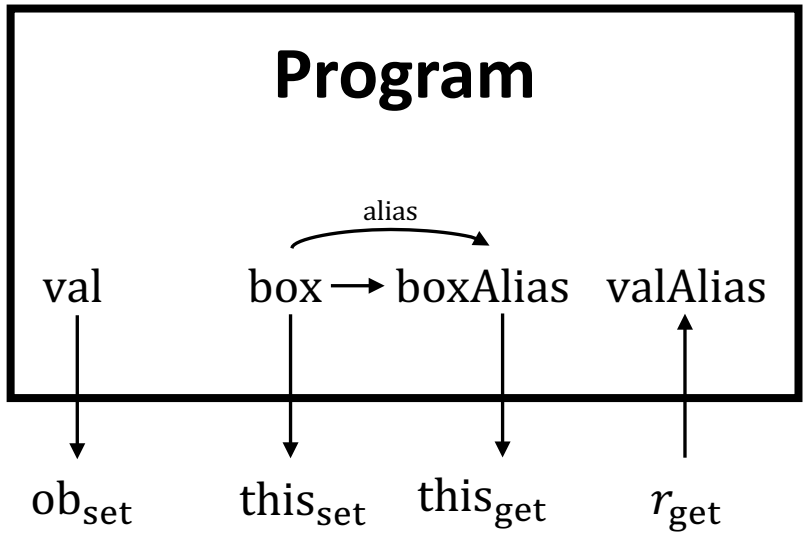

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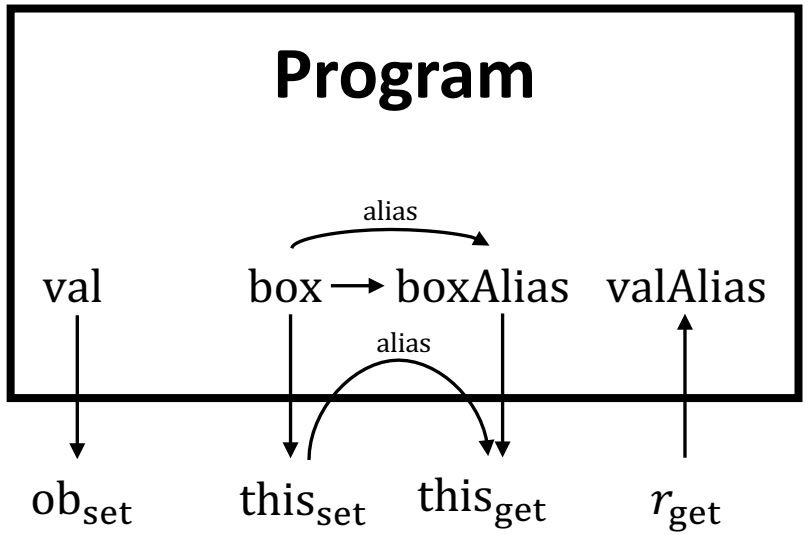

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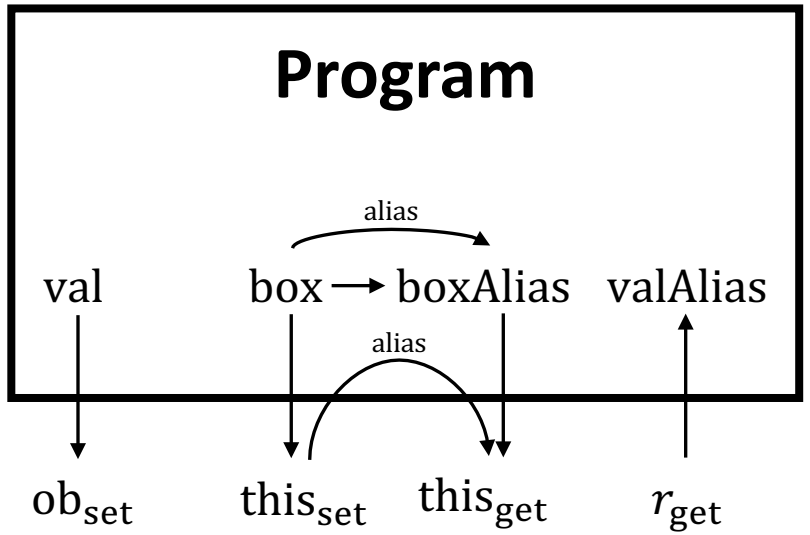
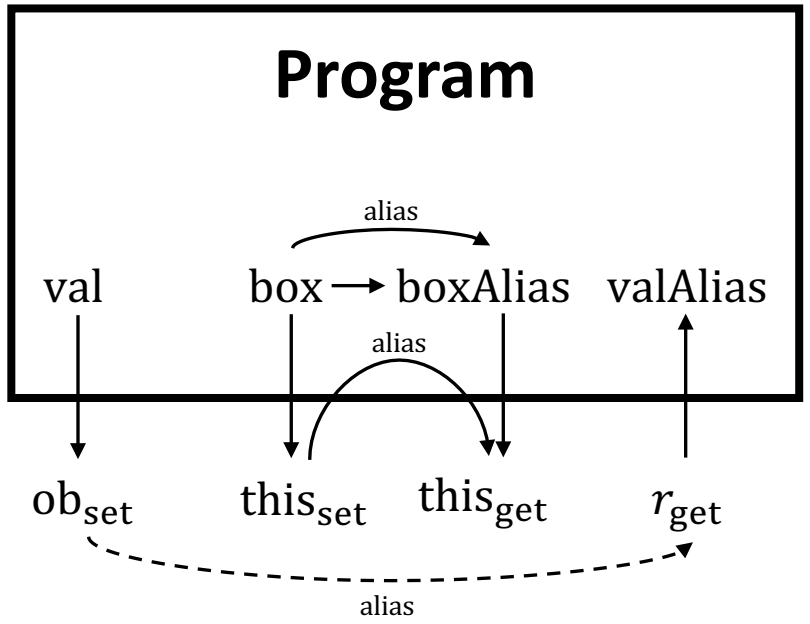
Roadmap

- Points-to analysis
- **Path specifications**
- Inference algorithm
- Evaluation

Path Specifications: Intuition



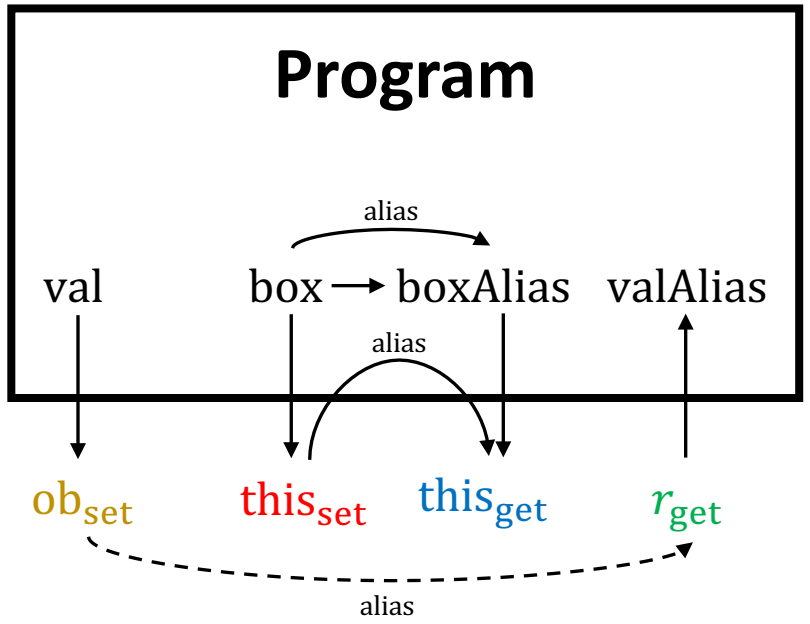
Path Specifications: Intuition



Path Specifications: Intuition

- When the library code is available, the edge $\text{ob}_{\text{set}} \xrightarrow{\text{alias}} r_{\text{get}}$ is produced by the path

$$\text{ob}_{\text{set}} \xrightarrow{\text{store}[f]} \text{this}_{\text{set}} \xrightarrow{\text{alias}} \text{this}_{\text{get}} \xrightarrow{\text{load}[f]} r_{\text{get}}$$



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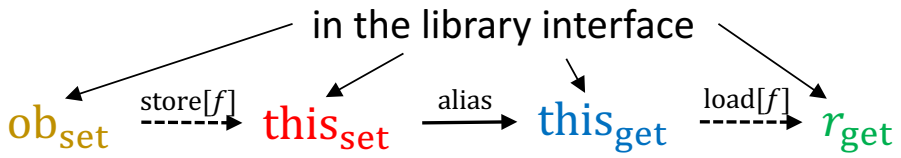

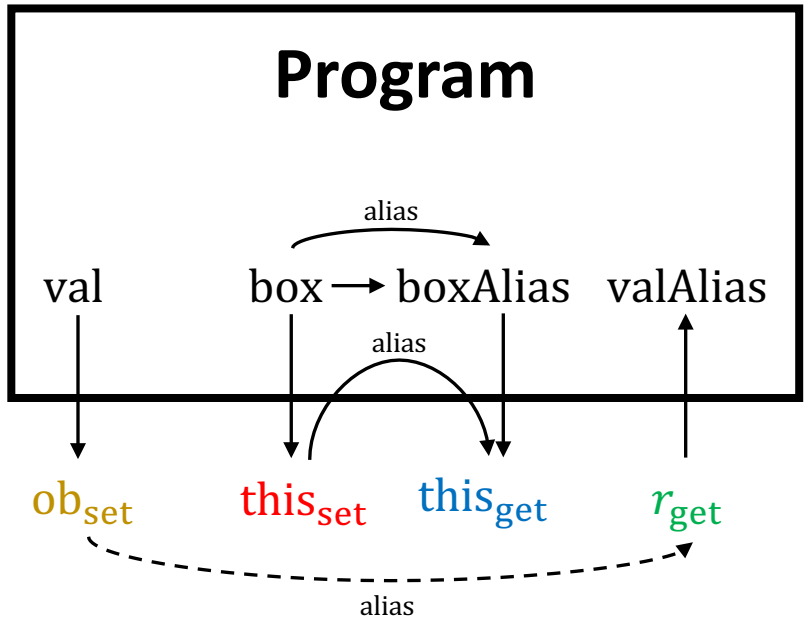

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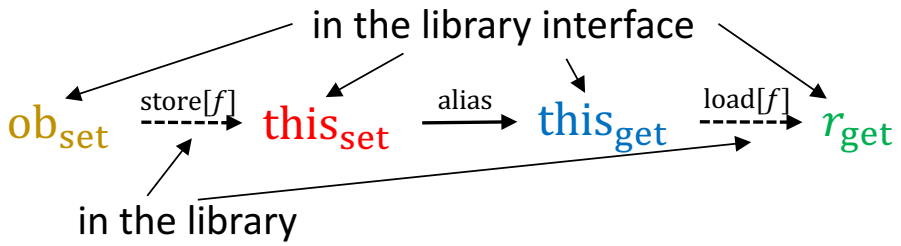

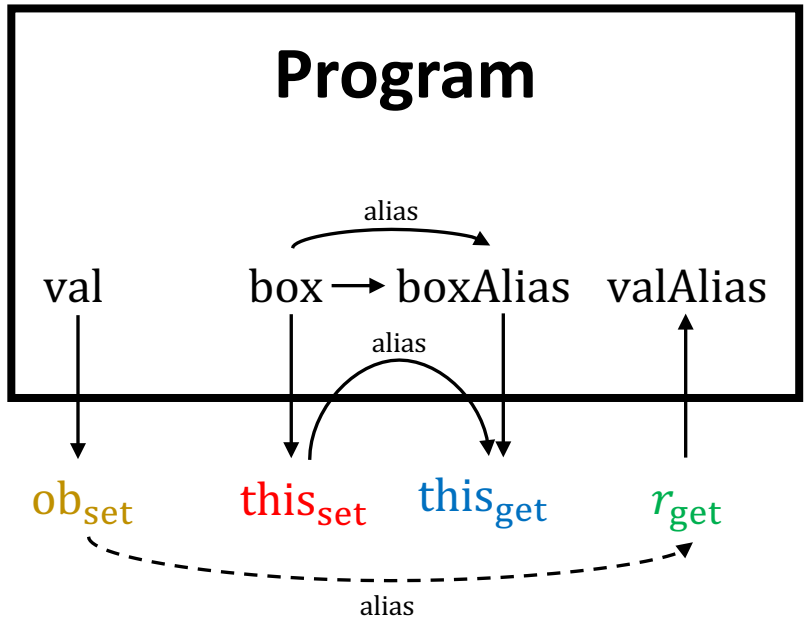

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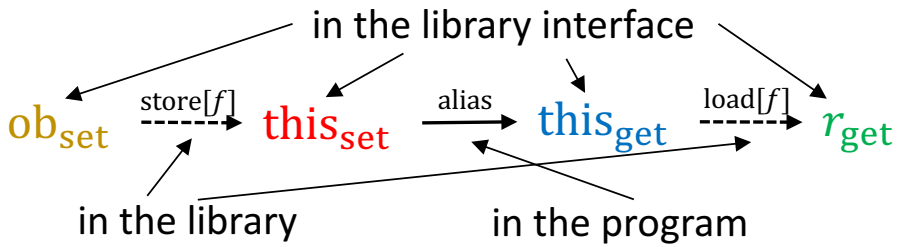

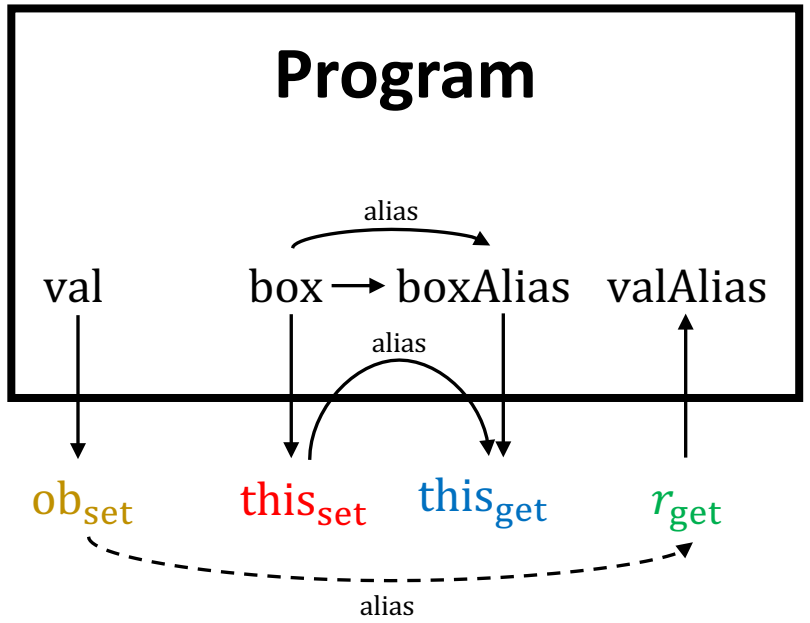

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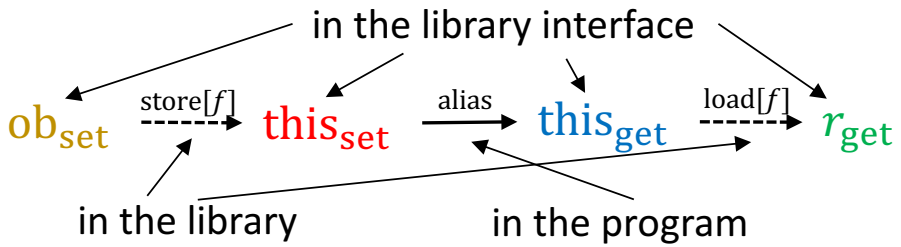
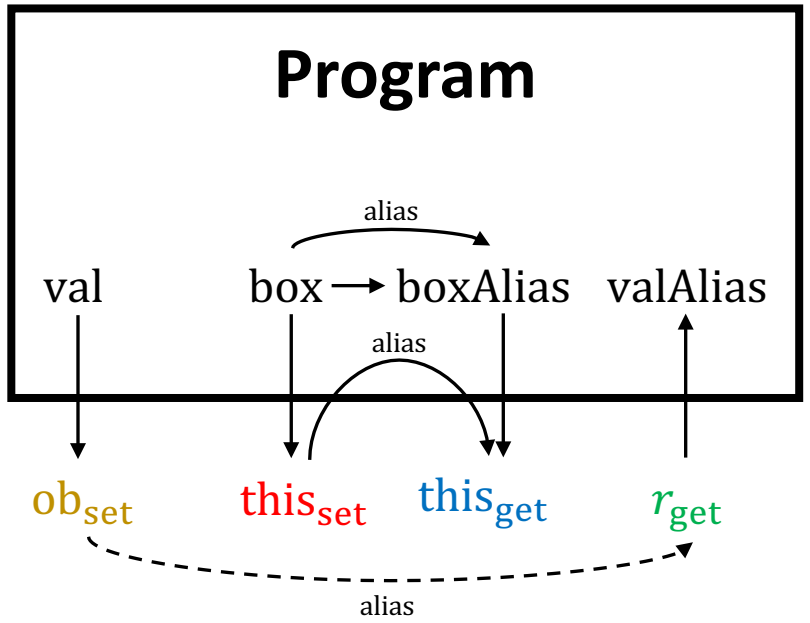


- A path specification says “if the solid edges are in the program, then the edges in the library complete them into a path that produces an alias edge”



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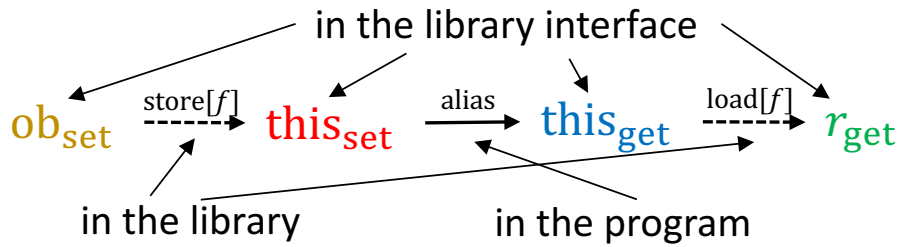

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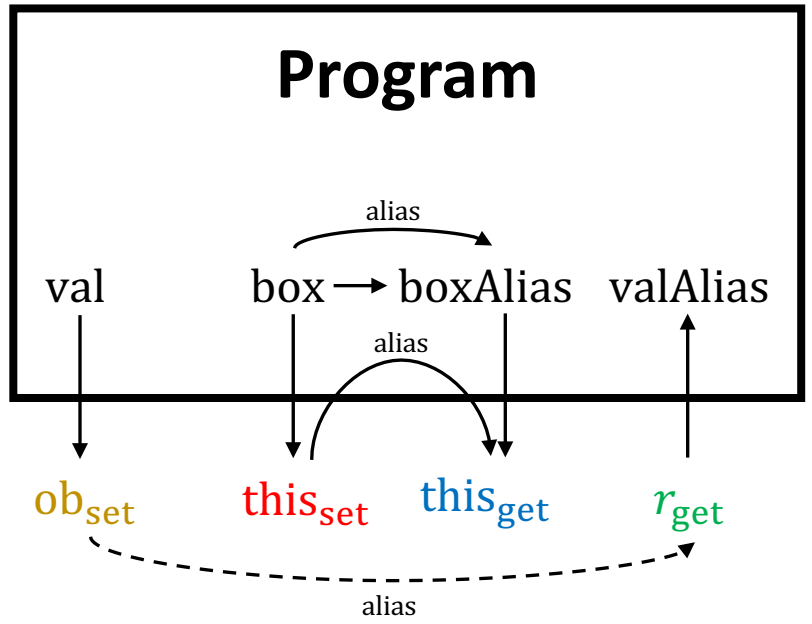

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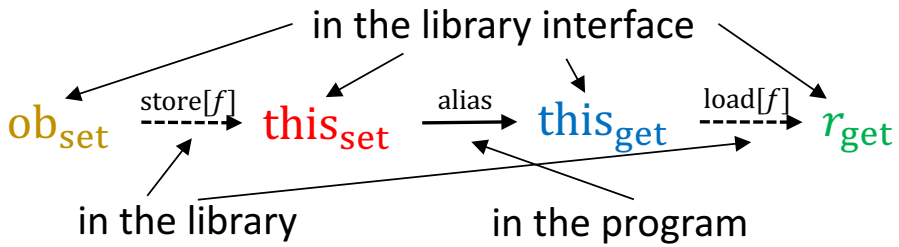

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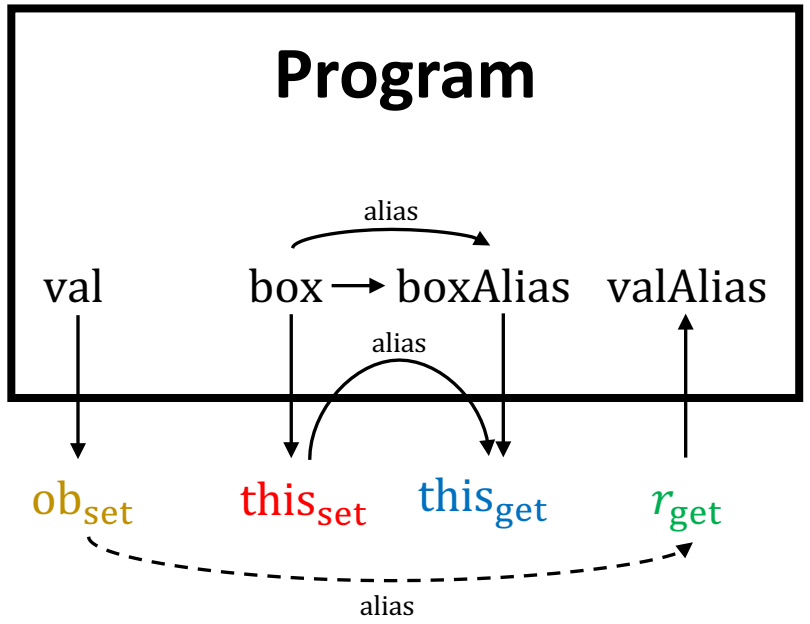

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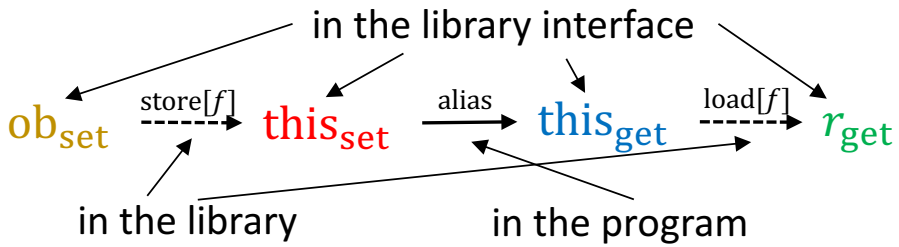

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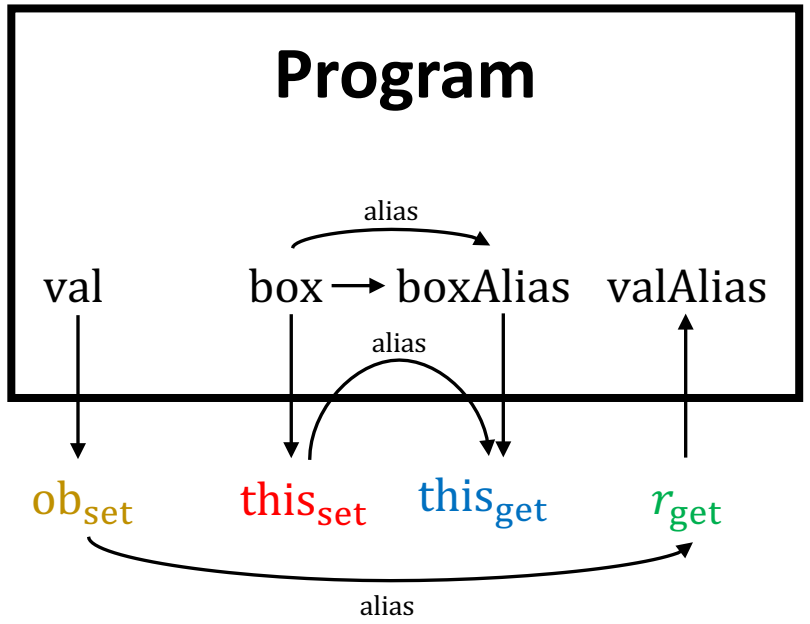

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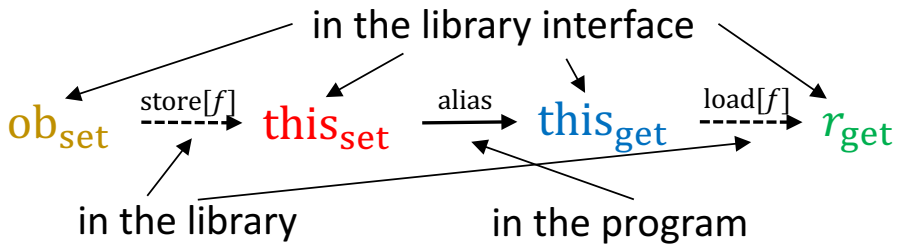

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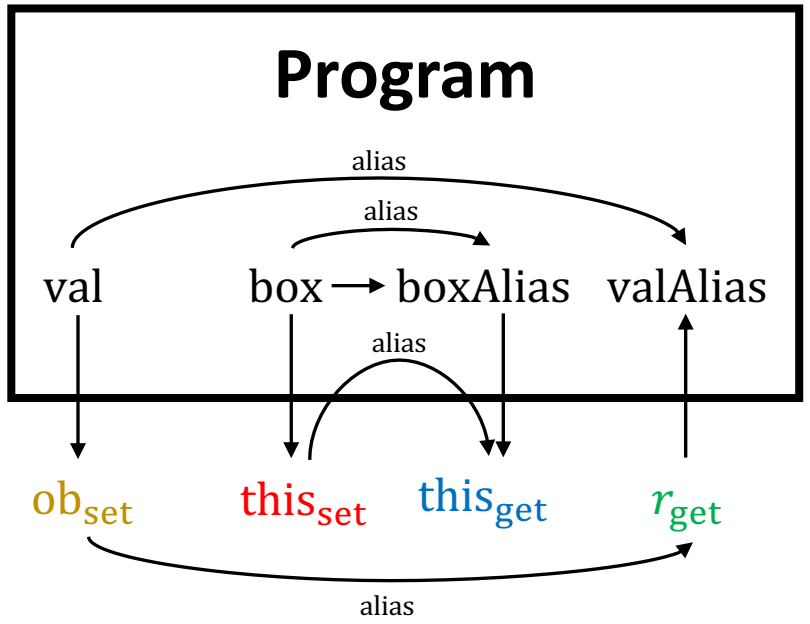

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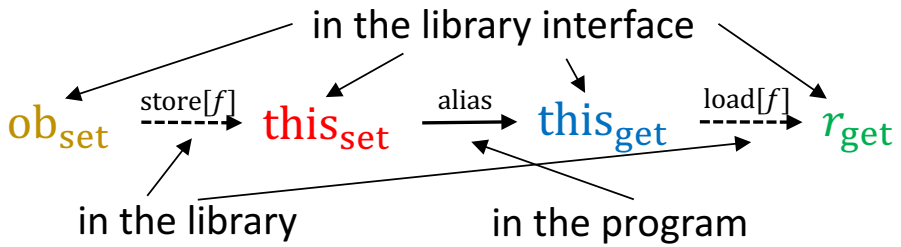

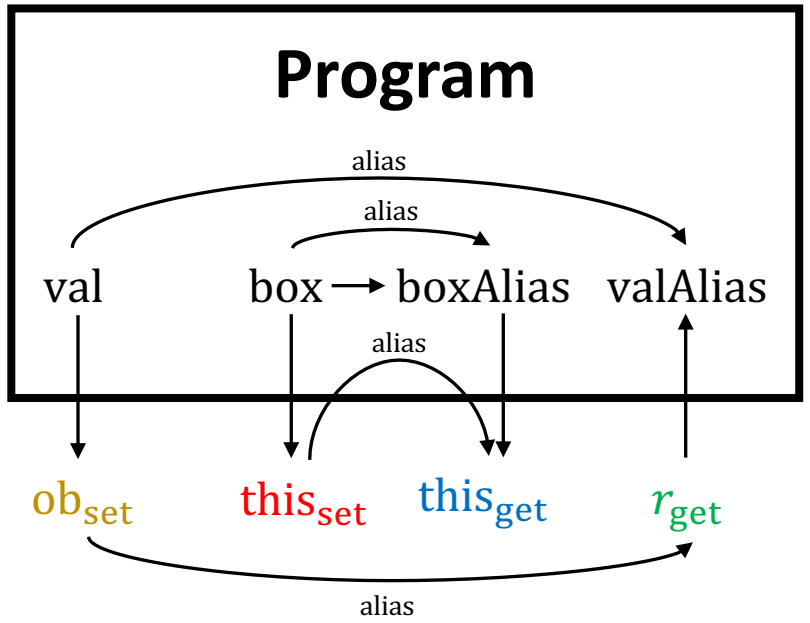

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Semantics: $\text{this}_{\text{set}} \xrightarrow{\text{alias}} \text{this}_{\text{get}} \Rightarrow \text{ob}_{\text{set}} \xrightarrow{\text{alias}} r_{\text{get}}$

- **Theorem:** It "suffices" to use path specifications where the solid edges are alias edges

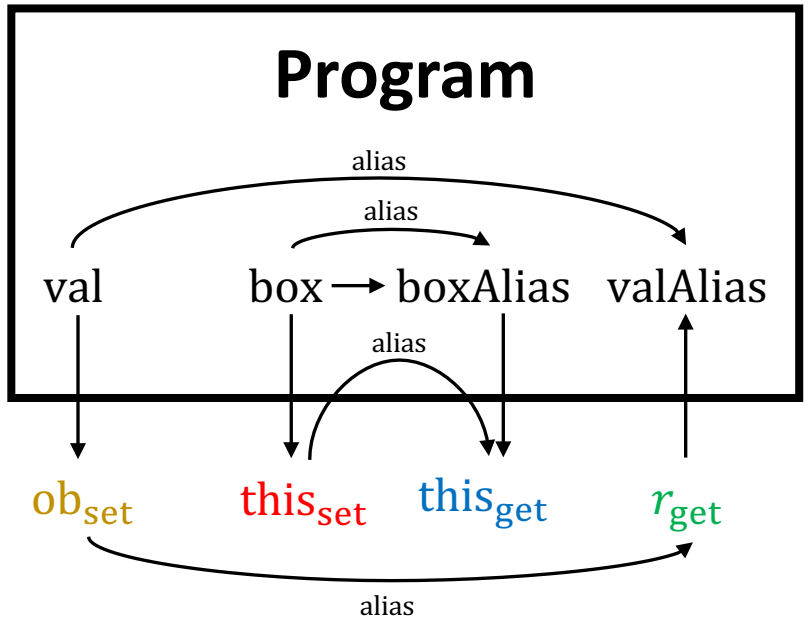
Path Specifications: Intuition

Syntax: A path specification is a sequence of library interface variables

$$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}} \rightarrow \mathrm{this}_{\mathrm{get}} \dashrightarrow r_{\mathrm{get}} \in V^*_{\mathrm{lib}}$$

Semantics: If the program edges in the path occur, then the path produces an alias edge

$$\mathrm{this}_{\mathrm{set}} \xrightarrow{\text{alias}} \mathrm{this}_{\mathrm{get}} \quad \Rightarrow \quad \mathrm{ob}_{\mathrm{set}} \xrightarrow{\text{alias}} r_{\mathrm{get}}$$



Path Specifications: Definition

- **Syntax**

$$z_1 \dashrightarrow w_1 \rightarrow z_2 \dashrightarrow w_2 \rightarrow z_3 \dashrightarrow \cdots \dashrightarrow w_{k-1} \rightarrow z_k \dashrightarrow w_k \in V^*_{\text{lib}}$$

where z_i, w_i are variables in the interface of library function f_i

- **Semantics**

$$w_1 \xrightarrow{\text{alias}} z_2 \wedge w_2 \xrightarrow{\text{alias}} z_3 \wedge \cdots \wedge w_{k-1} \xrightarrow{\text{alias}} z_k \Rightarrow z_1 \xrightarrow{\text{alias}} w_k$$

Issue with Path Specifications

- **Intuition:**

$$\text{sequence of library function calls in the program} \Rightarrow \text{alias relationship in the program}$$

- **Issue:** A different path specification is needed for every possible sequence of library function calls that may produce an alias edge

Infinite Sets of Path Specifications

Infinite Sets of Path Specifications

```
class Box:  // library
    Object f;
    void set(Object ob): f = ob;
    Object get(): return f;
    Object clone():
        Box b = new Box();
        b.f = f;
        return b;
```

Infinite Sets of Path Specifications

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class Box:  // library
    Object f;
    void set(Object ob): f = ob;
    Object get(): return f;
    Object clone():
        Box b = new Box();
        b.f = f;
        return b;
```

```
Object in = new Object();
Box box0 = new Box();
box0.add(in);
Object out = box0.get();
return in == out;
```

$$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}} \rightarrow \mathrm{this}_{\mathrm{get}} \dashrightarrow r_{\mathrm{get}}$$

Infinite Sets of Path Specifications

```
class Box:  // library
    Object f;
    void set(Object ob): f = ob;
    Object get(): return f;
    Object clone():
        Box b = new Box();
        b.f = f;
        return b;
```

```
Object in = new Object();
Box box0 = new Box();
box0.set(in);
Box box1 = box0.clone();
Object out = box1.get();
return in == out;
```

$$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}} \rightarrow \mathrm{this}_{\mathrm{clone}} \dashrightarrow r_{\mathrm{clone}} \rightarrow \mathrm{this}_{\mathrm{get}} \dashrightarrow r_{\mathrm{get}}$$

Infinite Sets of Path Specifications

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class Box:  // library
    Object f;
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Object in = new Object();
Box box0 = new Box();
box0.set(in);
Box box1 = box0.clone();
Box box2 = box1.clone();
Object out = box2.get();
return in == out;
```

$$\text{ob}_{\text{set}} \dashrightarrow \text{this}_{\text{set}} \rightarrow \text{this}_{\text{clone}} \dashrightarrow r_{\text{clone}} \rightarrow \text{this}_{\text{clone}} \dashrightarrow r_{\text{clone}} \rightarrow \text{this}_{\text{get}} \dashrightarrow r_{\text{get}}$$

Infinite Sets of Path Specifications

$$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}} (\rightarrow \mathrm{this}_{\mathrm{clone}} \dashrightarrow r_{\mathrm{clone}})^{*} \rightarrow \mathrm{this}_{\mathrm{get}} \dashrightarrow r_{\mathrm{get}} \subseteq V_{\mathrm{lib}}^{*}$$

Roadmap

- Motivating example
- Path specifications
- **Inference algorithm**
- Evaluation

Inference Algorithm

Inference Algorithm

Idea: Construct increasingly general sets of path specifications

Inference Algorithm

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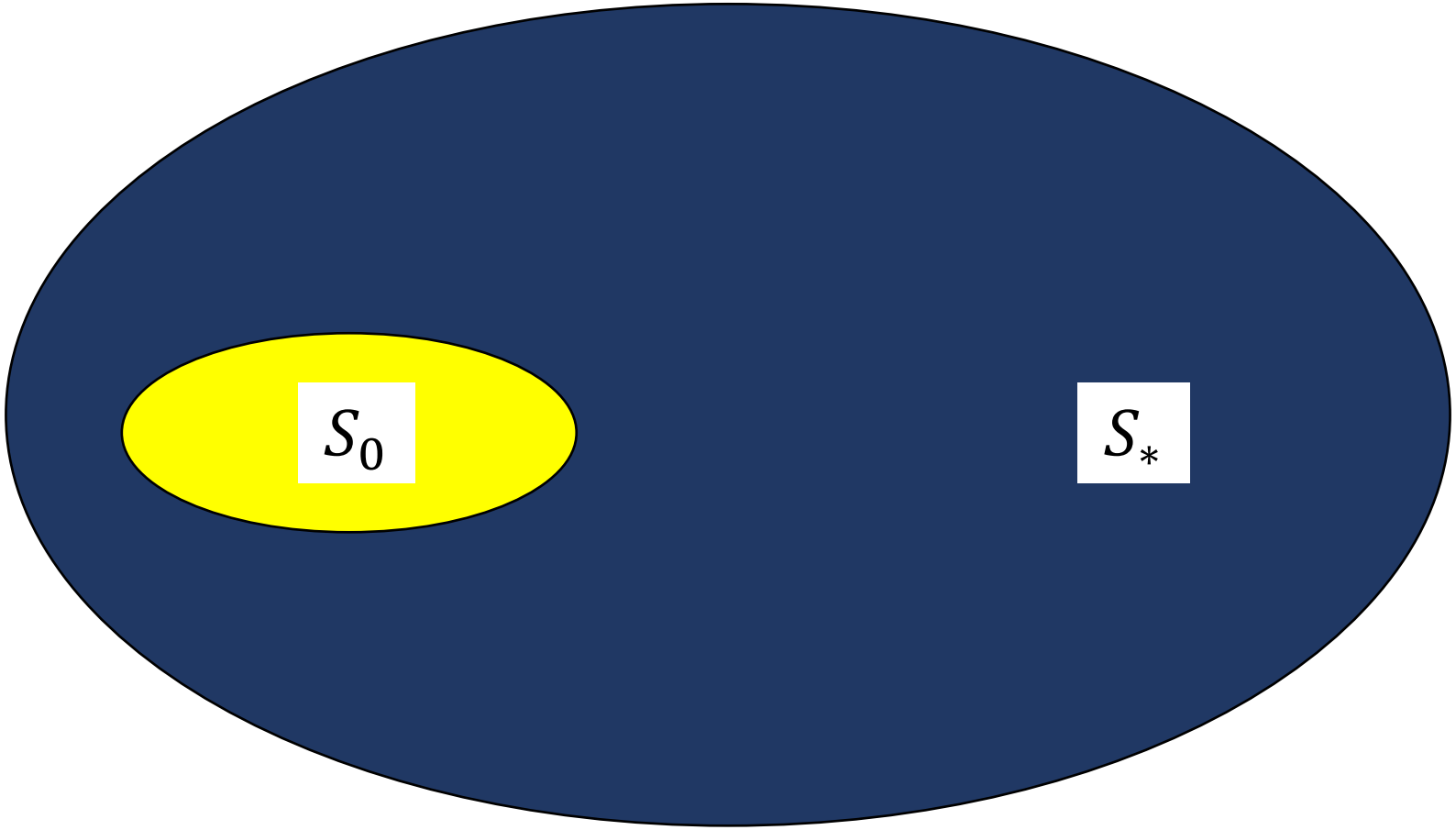
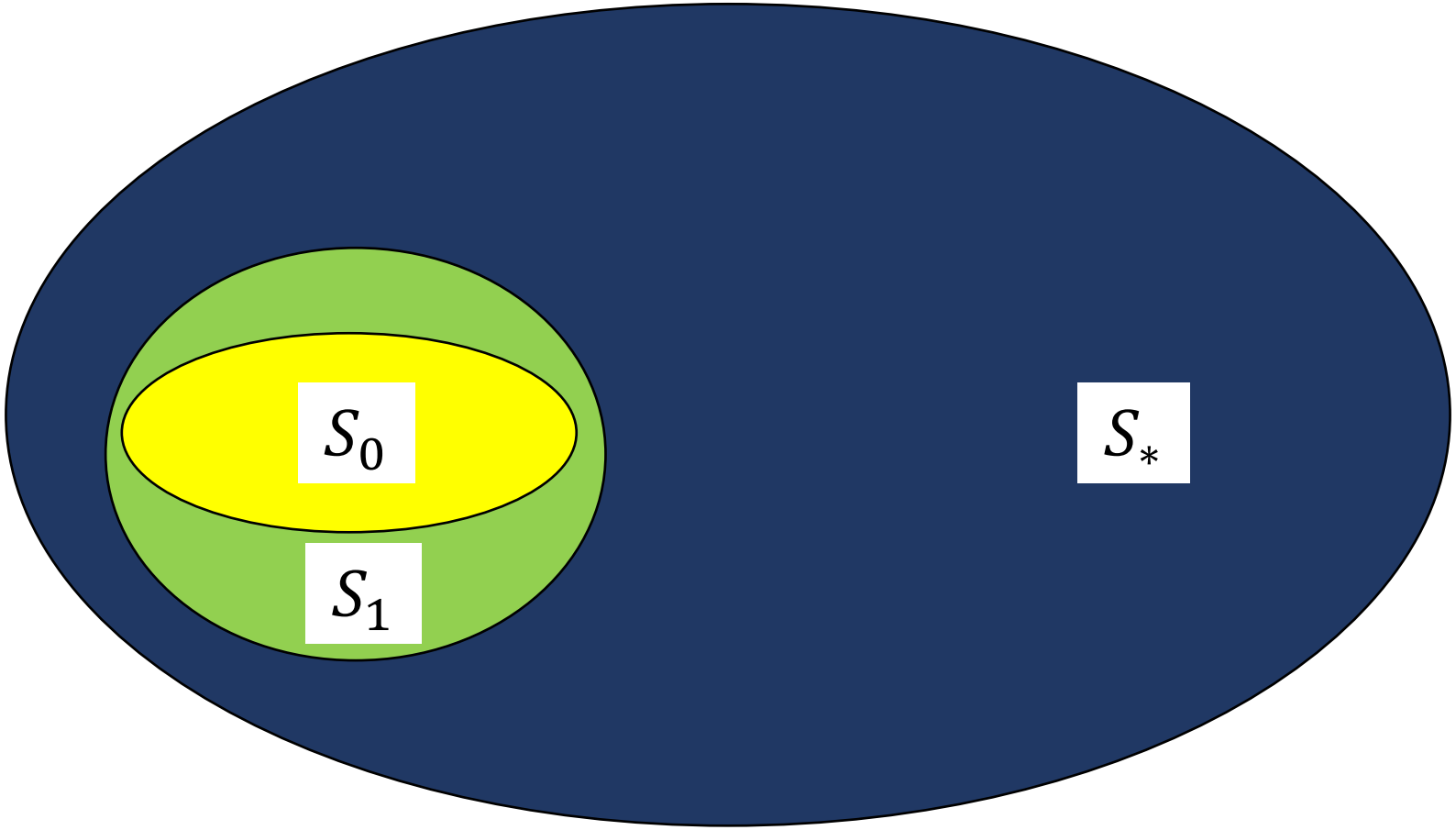
Inference Algorithm

Idea: Construct increasingly general sets of path specifications



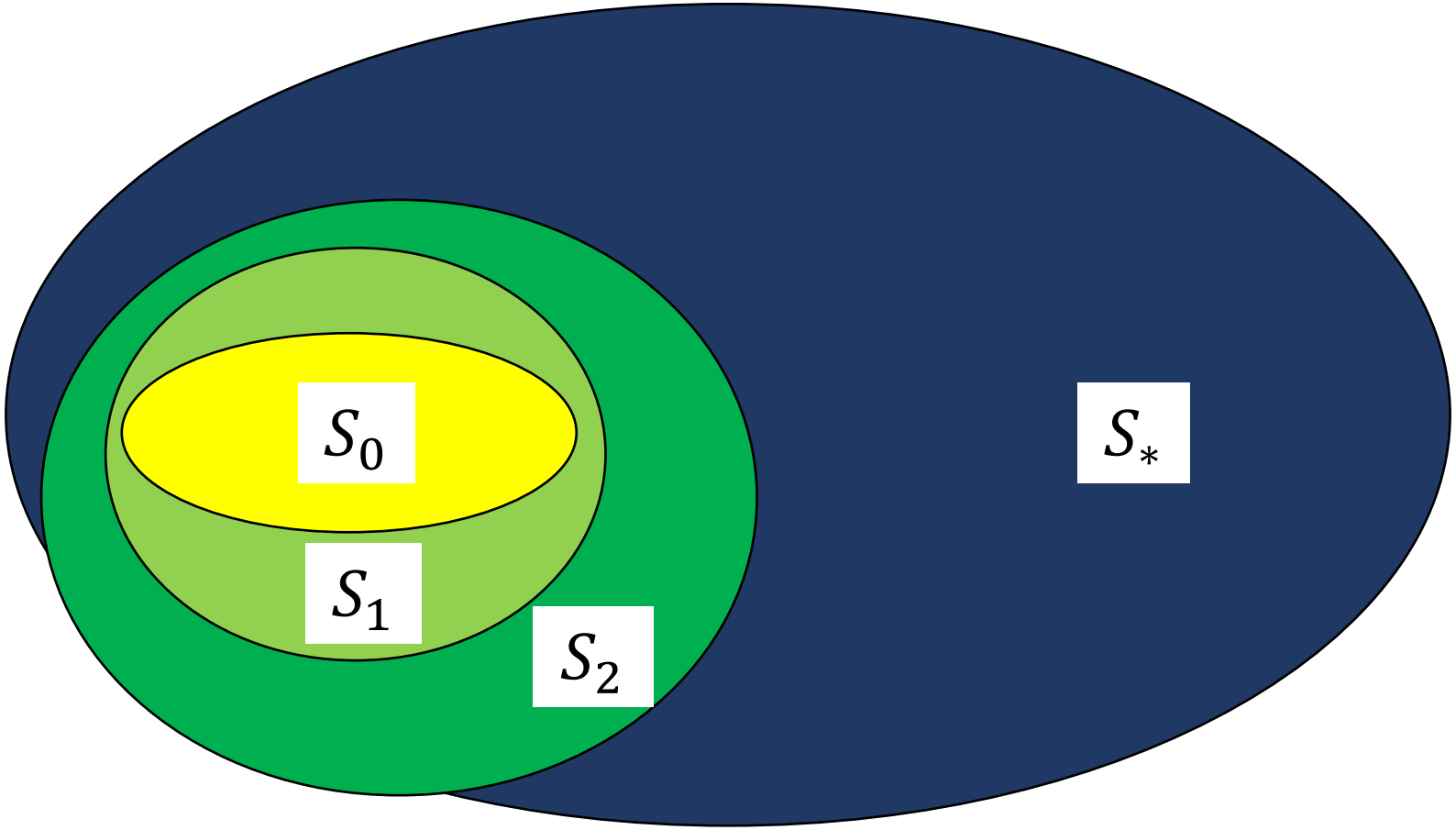
Inference Algorithm

Idea: Construct increasingly general sets of path specifications



Inference Algorithm

Idea: Construct increasingly general sets of path specifications



Inference Algorithm

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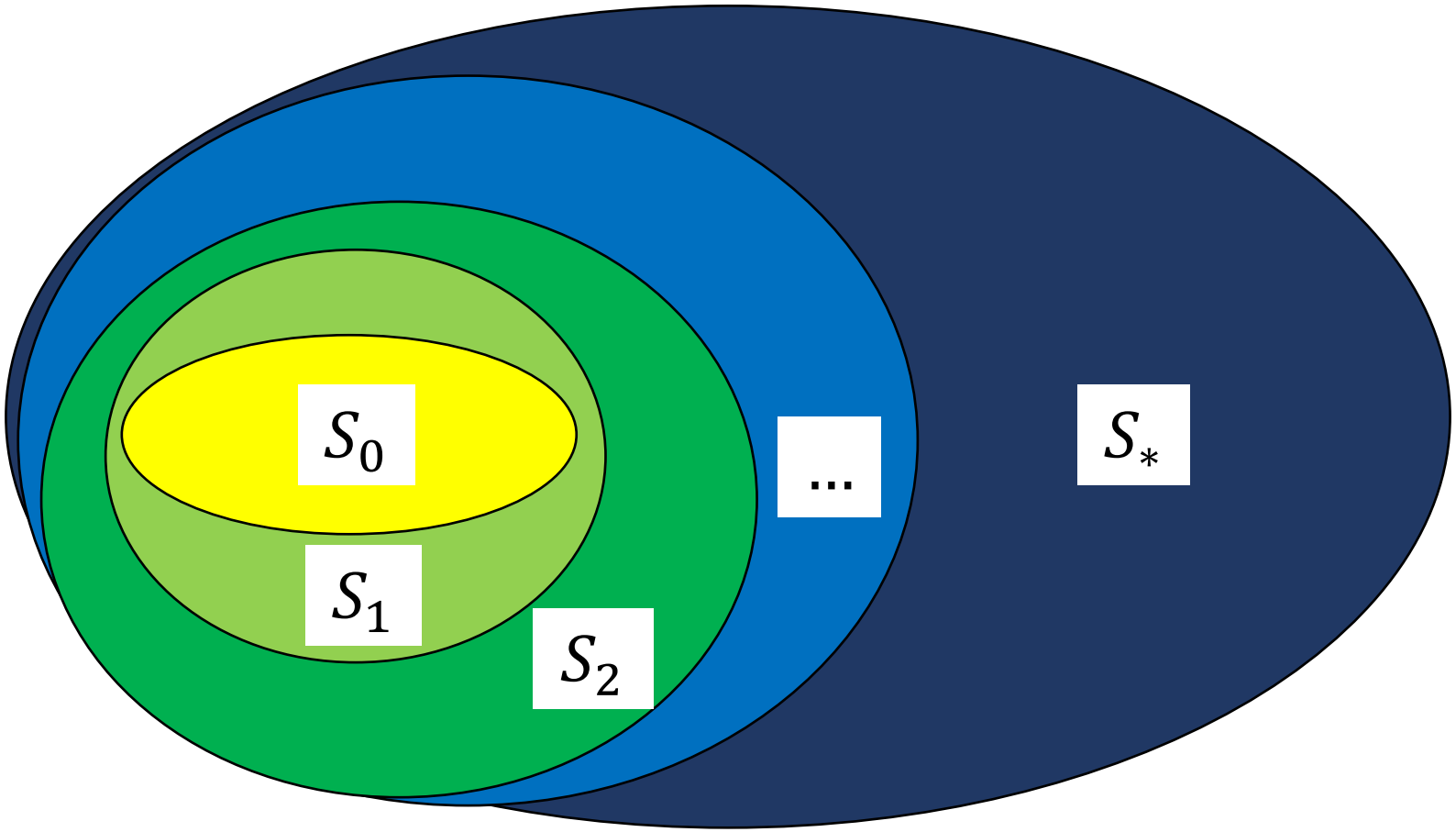

Inference Algorithm

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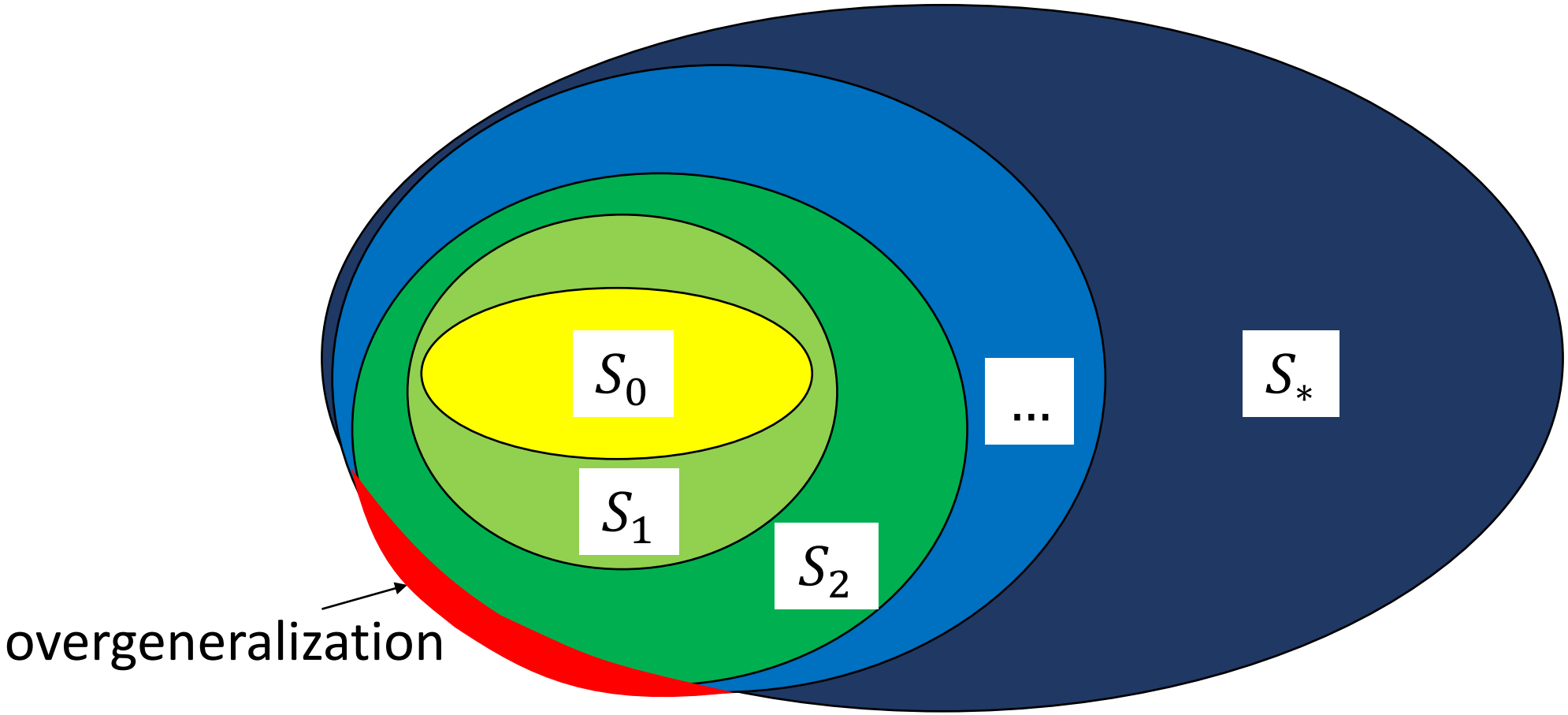


Inference Algorithm

Inference Algorithm

$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}}$
$\rightarrow \mathrm{this}_{\mathrm{get}} \dashrightarrow r_{\mathrm{get}}$

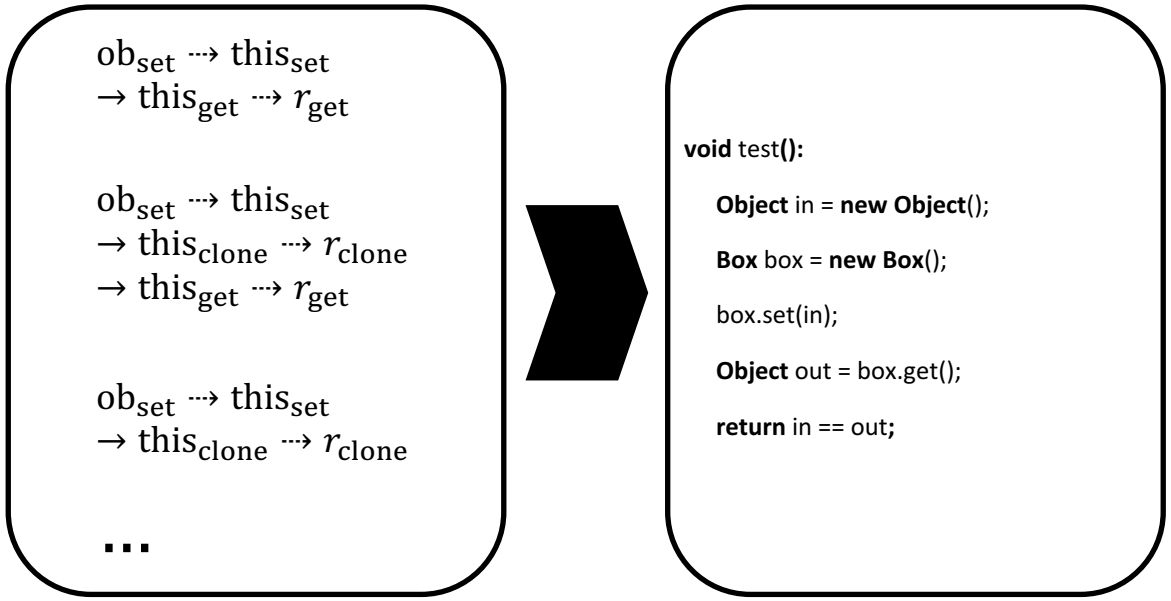
$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}}$
$\rightarrow \mathrm{this}_{\mathrm{clone}} \dashrightarrow r_{\mathrm{clone}}$
$\rightarrow \mathrm{this}_{\mathrm{get}} \dashrightarrow r_{\mathrm{get}}$

$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}}$
$\rightarrow \mathrm{this}_{\mathrm{clone}} \dashrightarrow r_{\mathrm{clone}}$

...

Step 1: Generate candidates

Inference Algorithm

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    Object in = new Object();
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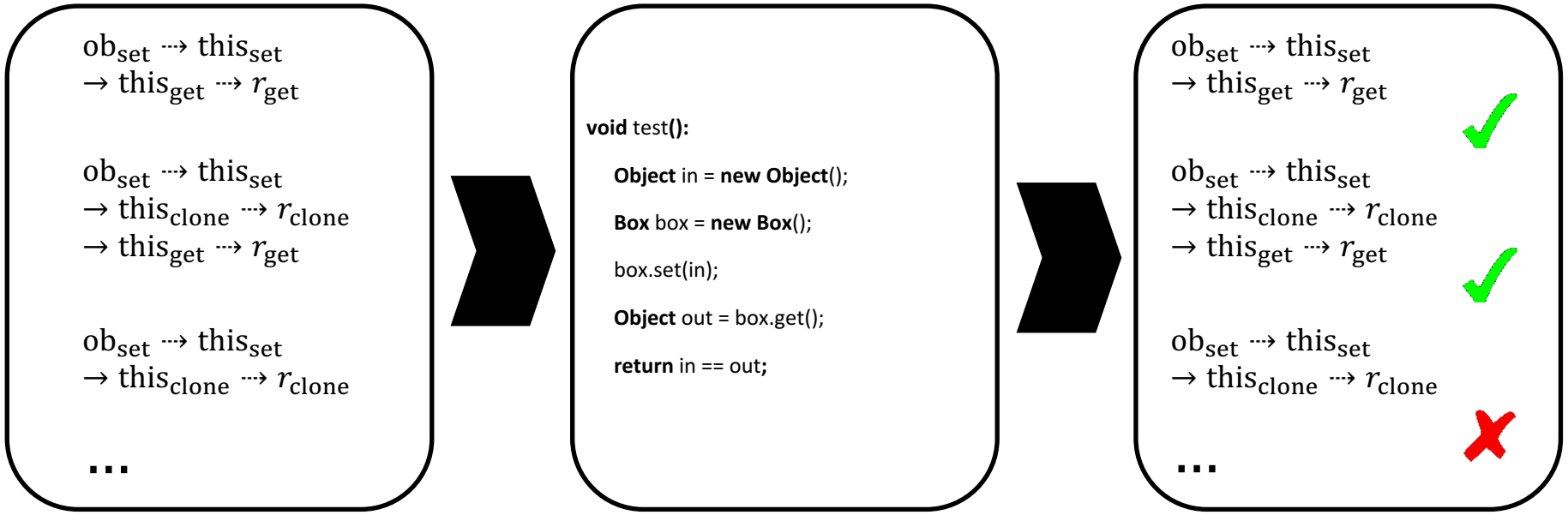
    Object out = box.get();
    return in == out;
```

Step 1: Generate candidates

Step 2a: Synthesize unit tests to check candidates

Inference Algorithm

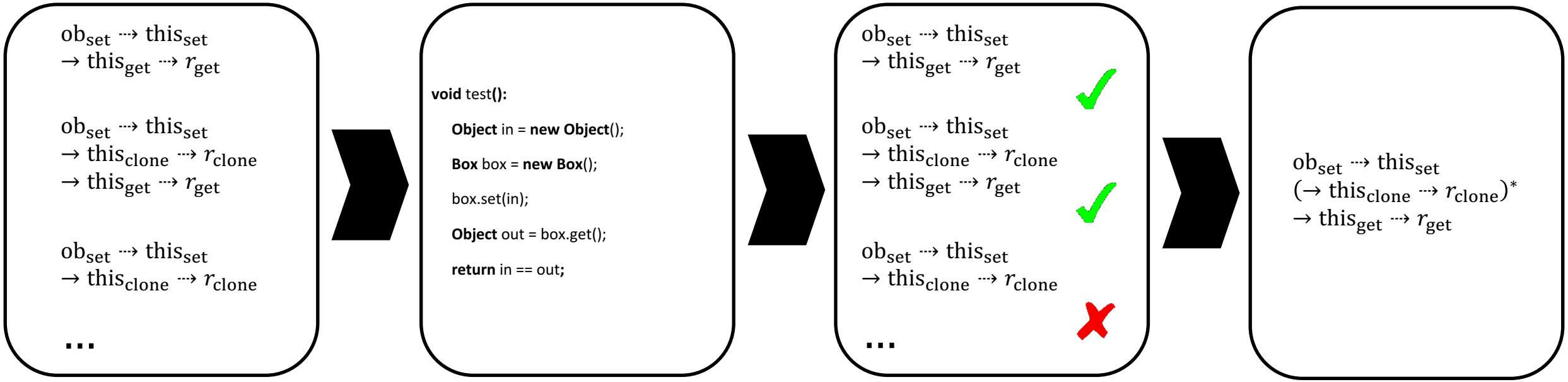


Step 1: Generate candidates

Step 2a: Synthesize unit tests to check candidates

Step 2b: Retain precise candidates S_0

Inference Algorithm



Step 1: Generate candidates

Step 2a: Synthesize unit tests to check candidates

Step 2b: Retain precise candidates S_0

Step 3: Generalize S_0 to a regular set

Generating Candidate Specifications

Generating Candidate Specifications

- A path specification is a sequence

$$z_1 w_1 z_2 w_2 \ldots z_k w_k \in V_{\text{lib}}^*$$

Generating Candidate Specifications

- A path specification is a sequence

$$z_1 w_1 z_2 w_2 \ldots z_k w_k \in V_{\text{lib}}^*$$

- **Algorithm:** We can use any sampling algorithm
  - Random sampling
  - Reinforcement learning (Monte Carlo tree search)

Unit Test Synthesis

Unit Test Synthesis

$$\mathrm{ob}_{\mathrm{set}} \dashrightarrow \mathrm{this}_{\mathrm{set}} \rightarrow \mathrm{this}_{\mathrm{get}} \dashrightarrow r_{\mathrm{get}}$$

$$\mathrm{this}_{\mathrm{set}} \xrightarrow{\text{alias}} \mathrm{this}_{\mathrm{get}} \quad \Rightarrow \quad \mathrm{ob}_{\mathrm{set}} \xrightarrow{\text{alias}} r_{\mathrm{get}}$$

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void test():

Unit Test Synthesis

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```
void test():
    ??.set(??);
    ?? = ??.get();
```

Unit Test Synthesis

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```
void test():
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```

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    box.set(in);
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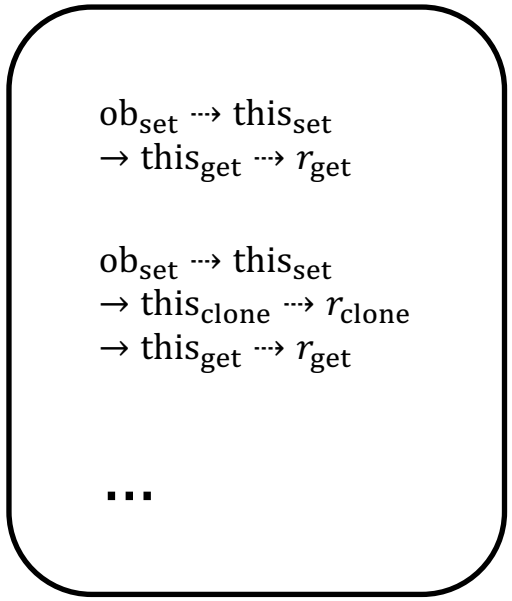
    return in == out;
```

Unit Test Synthesis

- **Guarantee:** Unit test returns true ⇒ candidate specification is precise
  - Converse is not true!
  - Works well in practice

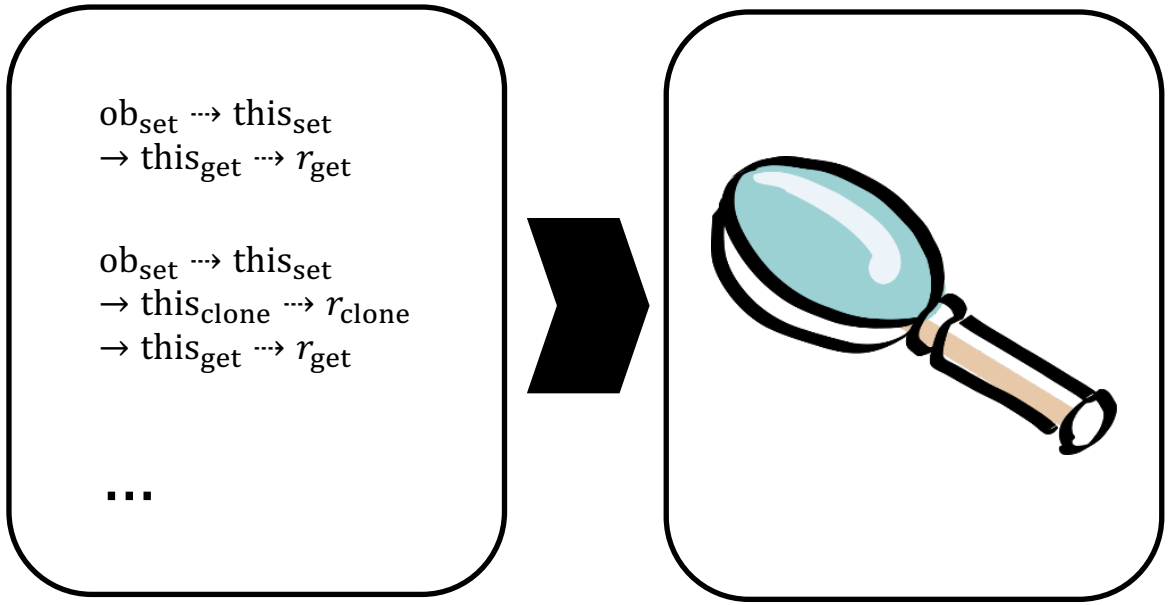
Generalizing to a Regular Set

Generalizing to a Regular Set



Inputs: Positive examples S_0

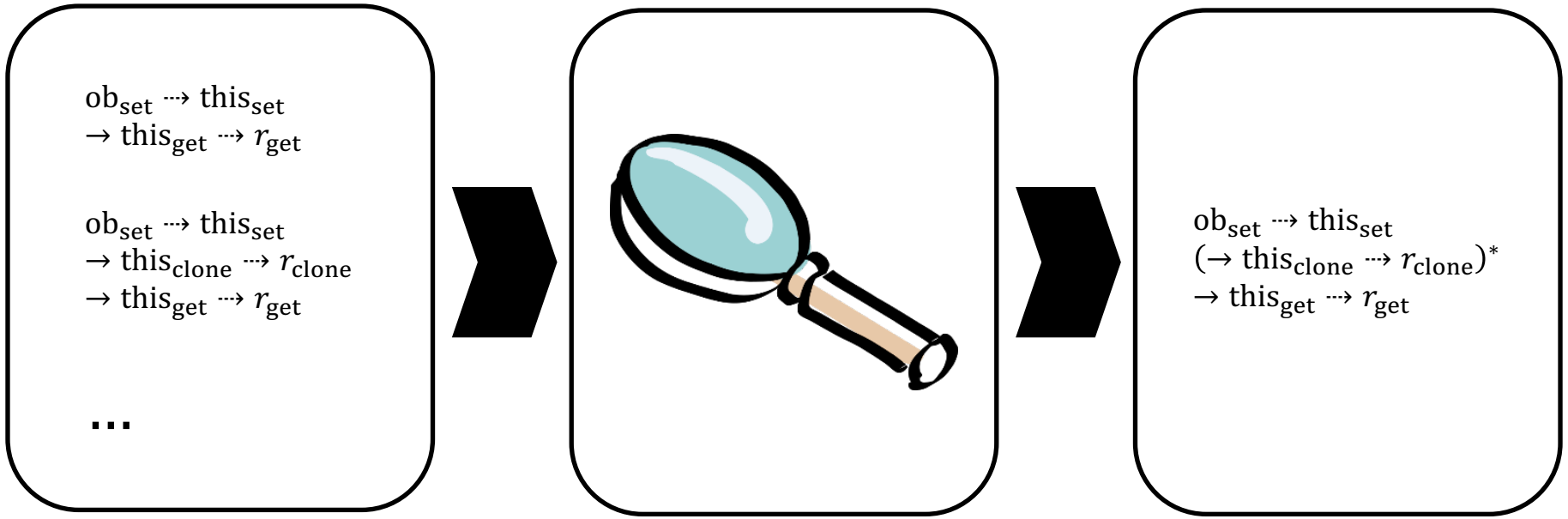
Generalizing to a Regular Set



Inputs: Positive examples S_0

Generalization: Language learning based on RPNI

Generalizing to a Regular Set



Inputs: Positive examples S_0

Generalization: Language learning based on RPNI

Output: Regular set of path specifications

Roadmap

- Motivating example
- Path specifications
- Inference algorithm
- **Evaluation**

Evaluation

- Focus on 12 most commonly used classes in the Java Collections API

- Comparisons
  - **Inferred specs:** Specifications inferred by our algorithm
  - **Ground truth specs:** Handwritten ground truth specifications (1700 LOC)
  - **Implementation:** The library implementation bytecode

- Metric for evaluating points-to analysis

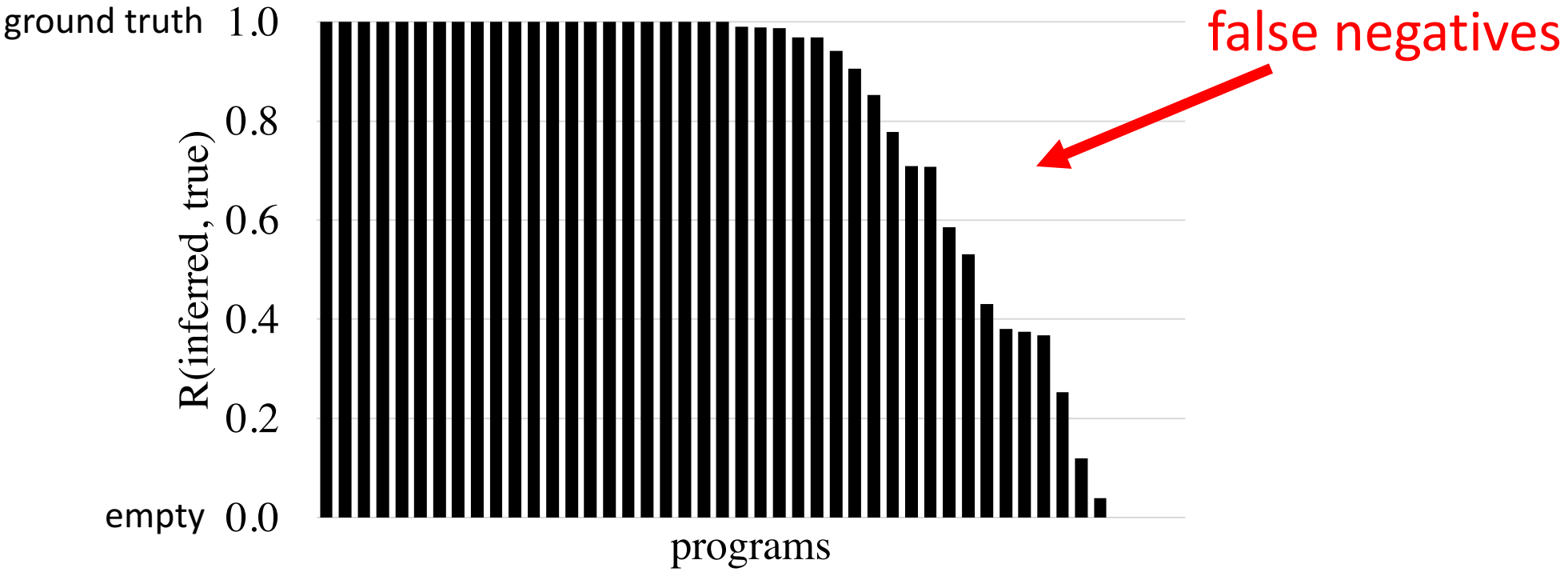
$$R(S, S') = \frac{\#\mathrm{pt}(S) - \#\mathrm{pt}(\emptyset)}{\#\mathrm{pt}(S') - \#\mathrm{pt}(\emptyset)}$$

- Benchmark of 46 programs

Inferred vs. Ground Truth (Specifications)

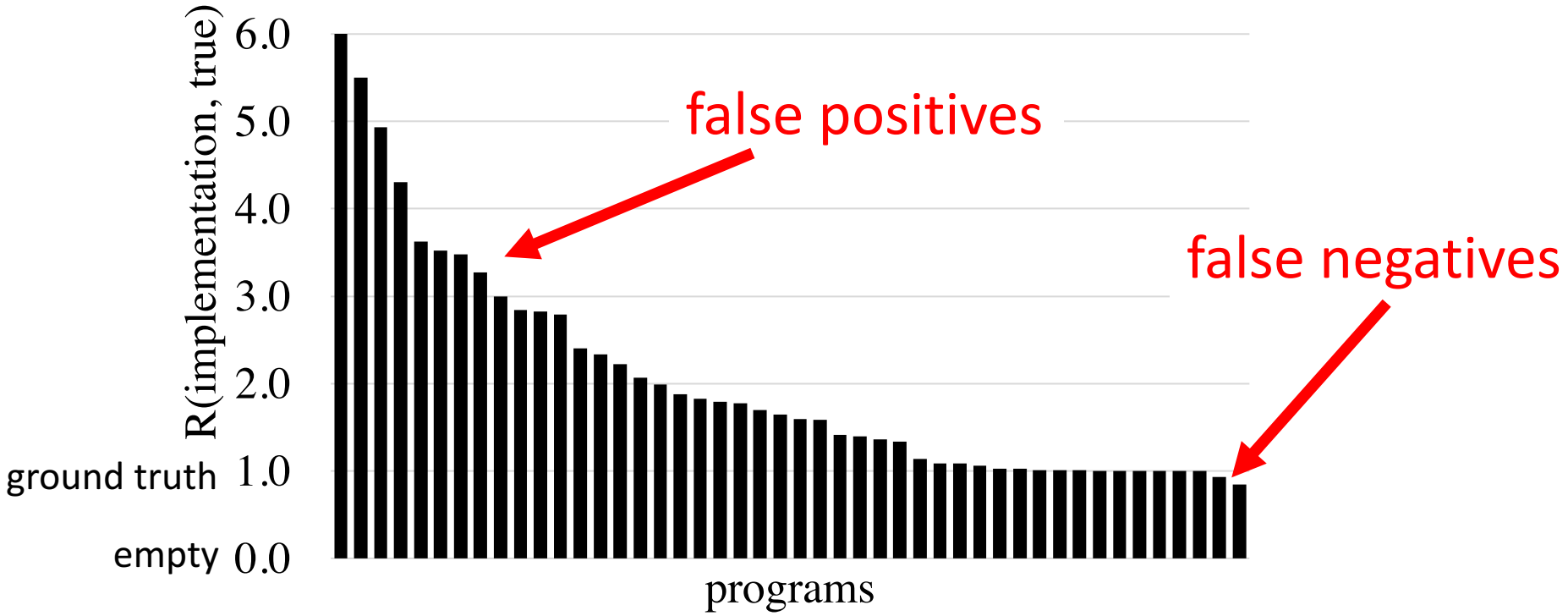
- Measured precision/recall on 50 most frequently used library functions
  - **Precision:** 100%
  - **Recall:** 97%

Inferred vs. Ground Truth (Points-To)



Average FN rate of inferred: 24%
Median FN rate of inferred: 1%

Implementation vs. Ground Truth



Average FP rate of implementation: 62%
Median FP rate of implementation: 115%

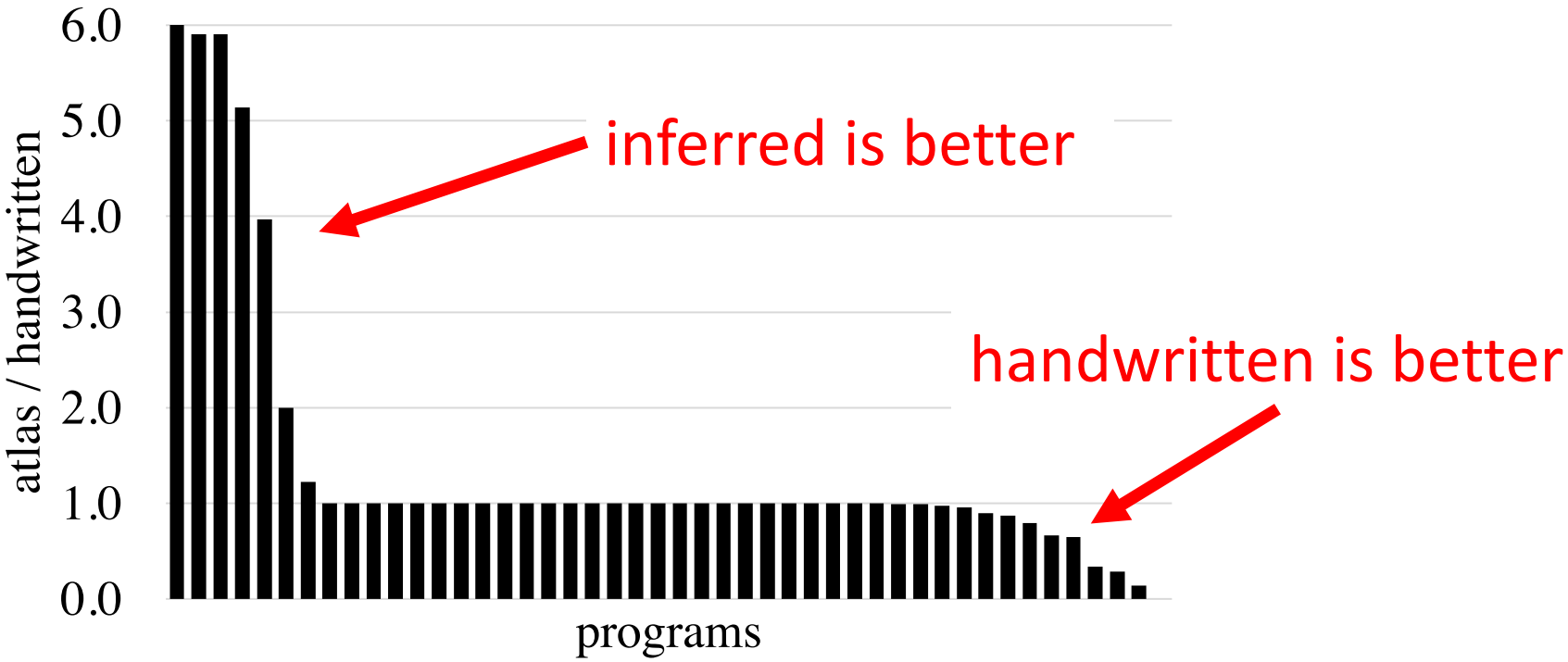
Conclusion

Specification inference can substantially improve the usability of static analysis tools

Inferred vs. Prior

- 878 inferred vs. 159 prior
- 89% recall

Inferred vs. Existing (Taint Flows)



inferred finds 52% more information flows